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# Advanced Machine Learning Lecture 10

## Mixture Models II

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## Announcement

- Exercise sheet 2 online
  - Sampling
  - Rejection Sampling
  - Importance Sampling
  - Metropolis-Hastings
  - EM
  - Mixtures of Bernoulli distributions [today's topic]
  - Exercise will be on Wednesday, 07.12.

⇒ Please submit your results until 06.12. midnight.

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## This Lecture: Advanced Machine Learning

- Regression Approaches
  - Linear Regression
  - Regularization (Ridge, Lasso)
  - Gaussian Processes
- Learning with Latent Variables
  - Probability Distributions
  - Approximate Inference
  - Mixture Models
  - EM and Generalizations
- Deep Learning
  - Neural Networks
  - CNNs, RNNs, RBMs, etc.

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## Topics of This Lecture

- The EM algorithm in general
  - Recap: General EM
  - Example: Mixtures of Bernoulli distributions
  - Monte Carlo EM
- Bayesian Mixture Models
  - Towards a full Bayesian treatment
  - Dirichlet priors
  - Finite mixtures
  - Infinite mixtures
  - Approximate inference (only as supplementary material)

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## Recap: Mixture of Gaussians

- "Generative model"
 
$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n | \mu_k, \Sigma_k)$$

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Image source: C. M. Bishop, 2006

Slide credit: Bernt Schiele

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## Recap: GMMs as Latent Variable Models

- Write GMMs in terms of latent variables  $\mathbf{z}$ 
  - Marginal distribution of  $\mathbf{x}$ 

$$p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z}) = \sum_{\mathbf{z}} p(\mathbf{z})p(\mathbf{x}|\mathbf{z}) = \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x} | \mu_k, \Sigma_k)$$
- Advantage of this formulation
  - We have represented the marginal distribution in terms of latent variables  $\mathbf{z}$ .
  - Since  $p(\mathbf{x}) = \sum_{\mathbf{z}} p(\mathbf{x}, \mathbf{z})$ , there is a corresponding latent variable  $\mathbf{z}_n$  for each data point  $\mathbf{x}_n$ .
  - We are now able to work with the joint distribution  $p(\mathbf{x}, \mathbf{z})$  instead of the marginal distribution  $p(\mathbf{x})$ .


⇒ This will lead to significant simplifications...

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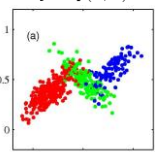
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**Recap: Sampling from a Gaussian Mixture**

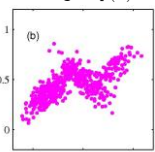
- MoG Sampling
  - We can use **ancestral sampling** to generate random samples from a Gaussian mixture model.
    - Generate a value  $\tilde{z}$  from the marginal distribution  $p(\mathbf{z})$ .
    - Generate a value  $\tilde{\mathbf{x}}$  from the conditional distribution  $p(\mathbf{x}|\tilde{\mathbf{z}})$ .



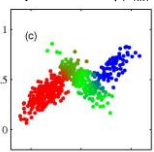
Samples from the joint  $p(\mathbf{x}, \mathbf{z})$



Samples from the marginal  $p(\mathbf{x})$



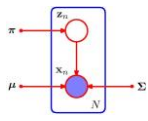
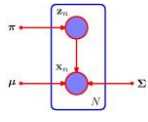
Evaluating the responsibilities  $\gamma(z_{nk})$



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Image source: C.M. Bishop, 2006

**Recap: Gaussian Mixtures Revisited**

- Applying the latent variable view of EM
  - Goal is to maximize the log-likelihood using the observed data  $\mathbf{X}$ 

$$\log p(\mathbf{X}|\theta) = \log \left\{ \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\theta) \right\}$$
  - Corresponding graphical model:
 
  - Suppose we are additionally given the values of the latent variables  $\mathbf{Z}$ .
    - The corresponding graphical model for the complete data now looks like this:
 
    - ⇒ Straightforward to marginalize...

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Image source: C.M. Bishop, 2006

**Recap: Alternative View of EM**

- In practice, however,...
  - We are not given the complete data set  $\{\mathbf{X}, \mathbf{Z}\}$ , but only the incomplete data  $\mathbf{X}$ . All we can compute about  $\mathbf{Z}$  is the posterior distribution  $p(\mathbf{Z}|\mathbf{X}, \theta)$ .
  - Since we cannot use the complete-data log-likelihood, we consider instead its **expected value under the posterior distribution of the latent variable**:
 
$$Q(\theta, \theta^{\text{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}}) \log p(\mathbf{X}, \mathbf{Z}|\theta)$$
  - This corresponds to the **E-step** of the EM algorithm.
  - In the subsequent **M-step**, we then maximize the expectation to obtain the revised parameter set  $\theta^{\text{new}}$ .
 
$$\theta^{\text{new}} = \arg \max_{\theta} Q(\theta, \theta^{\text{old}})$$

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**Recap: General EM Algorithm**

- Algorithm
  - Choose an initial setting for the parameters  $\theta^{\text{old}}$
  - E-step:** Evaluate  $p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}})$
  - M-step:** Evaluate  $\theta^{\text{new}}$  given by
 
$$\theta^{\text{new}} = \arg \max_{\theta} Q(\theta, \theta^{\text{old}})$$
 where
 
$$Q(\theta, \theta^{\text{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}}) \log p(\mathbf{X}, \mathbf{Z}|\theta)$$
  - While not converged, let  $\theta^{\text{old}} \leftarrow \theta^{\text{new}}$  and return to step 2.

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**Recap: MAP-EM**

- Modification for MAP
  - The EM algorithm can be adapted to find MAP solutions for models for which a prior  $p(\theta)$  is defined over the parameters.
  - Only changes needed:
    - E-step:** Evaluate  $p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}})$
    - M-step:** Evaluate  $\theta^{\text{new}}$  given by
 
$$\theta^{\text{new}} = \arg \max_{\theta} Q(\theta, \theta^{\text{old}}) + \log p(\theta)$$

⇒ Suitable choices for the prior will remove the ML singularities!

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**Gaussian Mixtures Revisited**

- Maximize the likelihood
  - For the complete-data set  $\{\mathbf{X}, \mathbf{Z}\}$ , the likelihood has the form
 
$$p(\mathbf{X}, \mathbf{Z}|\mu, \Sigma, \pi) = \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}} \mathcal{N}(\mathbf{x}_n|\mu_k, \Sigma_k)^{z_{nk}}$$
  - Taking the logarithm, we obtain
 
$$\log p(\mathbf{X}, \mathbf{Z}|\mu, \Sigma, \pi) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \{ \log \pi_k + \log \mathcal{N}(\mathbf{x}_n|\mu_k, \Sigma_k) \}$$
  - Compared to the incomplete-data case, the order of the sum and logarithm has been interchanged.
    - ⇒ Much simpler solution to the ML problem.
    - Maximization w.r.t. a mean or covariance is exactly as for a single Gaussian, except that it involves only the subset of data points that are "assigned" to that component.

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## Gaussian Mixtures Revisited

- Maximization w.r.t. mixing coefficients
  - More complex, since the  $\pi_k$  are coupled by the summation constraint
 
$$\sum_{j=1}^K \pi_j = 1$$
  - Solve with a Lagrange multiplier
 
$$\log p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}) + \lambda \left( \sum_{k=1}^K \pi_k - 1 \right)$$
  - Solution (after a longer derivation):
 
$$\pi_k = \frac{1}{N} \sum_{n=1}^N z_{nk}$$

⇒ The complete-data log-likelihood can be maximized trivially in closed form.

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## Gaussian Mixtures Revisited

- In practice, we don't have values for the latent variables
  - Consider the expectation w.r.t. the posterior distribution of the latent variables instead.
  - The posterior distribution takes the form
 
$$p(\mathbf{Z} | \mathbf{X}, \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi}) \propto \prod_{n=1}^N \prod_{k=1}^K [\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)]^{z_{nk}}$$

and factorizes over  $n$ , so that the  $\{z_n\}$  are independent under the posterior.

Expected value of indicator variable  $z_{nk}$  under the posterior.

$$\mathbb{E}[z_{nk}] = \frac{\sum_{z_{nk}} z_{nk} [\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)]^{z_{nk}}}{\sum_{z_{nj}} [\pi_j \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)]^{z_{nj}}}$$

$$= \frac{\pi_k \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)} = \gamma(z_{nk})$$

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## Gaussian Mixtures Revisited

- Continuing the estimation
  - The complete-data log-likelihood is therefore
 
$$\mathbb{E}_{\mathbf{Z}}[\log p(\mathbf{X}, \mathbf{Z} | \boldsymbol{\mu}, \boldsymbol{\Sigma}, \boldsymbol{\pi})] = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \{ \log \pi_k + \log \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k) \}$$

⇒ This is precisely the EM algorithm for Gaussian mixtures as derived before.

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## Summary So Far

- We have now seen a generalized EM algorithm
  - Applicable to general estimation problems with latent variables
  - In particular, also applicable to mixtures of other base distributions
  - In order to get some familiarity with the general EM algorithm, let's apply it to a different class of distributions...

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## Topics of This Lecture

- The EM algorithm in general
  - Recap: General EM
  - Example: Mixtures of Bernoulli distributions
  - Monte Carlo EM
- Bayesian Mixture Models
  - Towards a full Bayesian treatment
  - Dirichlet priors
  - Finite mixtures
  - Infinite mixtures
  - Approximate inference (only as supplementary material)

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## Mixtures of Bernoulli Distributions

- Discrete binary variables
  - Consider  $D$  binary variables  $\mathbf{x} = (x_1, \dots, x_D)^T$ , each of them described by a Bernoulli distribution with parameter  $\mu_i$ , so that
 
$$p(\mathbf{x} | \boldsymbol{\mu}) = \prod_{i=1}^D \mu_i^{x_i} (1 - \mu_i)^{(1-x_i)}$$
  - Mean and covariance are given by
 
$$\mathbb{E}[\mathbf{x}] = \boldsymbol{\mu}$$

$$\text{cov}[\mathbf{x}] = \text{diag} \{ \boldsymbol{\mu}(1 - \boldsymbol{\mu}) \}$$

Diagonal covariance  
⇒ variables independently modeled

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## Mixtures of Bernoulli Distributions

- Mixtures of discrete binary variables
  - Now, consider a finite mixture of those distributions
 
$$p(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\pi}) = \sum_{k=1}^K \pi_k p(\mathbf{x}|\boldsymbol{\mu}_k)$$

$$= \sum_{k=1}^K \pi_k \prod_{i=1}^D \mu_{ki}^{x_i} (1 - \mu_{ki})^{(1-x_i)}$$
  - Mean and covariance of the mixture are given by
 
$$\mathbb{E}[\mathbf{x}] = \sum_{k=1}^K \pi_k \boldsymbol{\mu}_k$$

Covariance not diagonal  
⇒ Model can capture dependencies between variables

$$\text{cov}[\mathbf{x}] = \sum_{k=1}^K \pi_k \{ \boldsymbol{\Sigma}_k + \boldsymbol{\mu}_k \boldsymbol{\mu}_k^T \} - \mathbb{E}[\mathbf{x}] \mathbb{E}[\mathbf{x}]^T$$

where  $\boldsymbol{\Sigma}_k = \text{diag}\{\mu_{ki}(1 - \mu_{ki})\}$ .

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## Mixtures of Bernoulli Distributions

- Log-likelihood for the model
  - Given a data set  $\mathbf{X} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ ,
 
$$\log p(\mathbf{X}|\boldsymbol{\mu}, \boldsymbol{\pi}) = \sum_{n=1}^N \log \left\{ \sum_{k=1}^K \pi_k p(\mathbf{x}_n|\boldsymbol{\mu}_k) \right\}$$
  - Again observation: summation inside logarithm ⇒ difficult.
  - In the following, we will derive the EM algorithm for mixtures of Bernoulli distributions.
    - This will show how we can derive EM algorithms in the general case...

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## EM for Bernoulli Mixtures

- Latent variable formulation
  - Introduce latent variable  $\mathbf{z} = (z_1, \dots, z_K)^T$  with 1-of-K coding.
  - Conditional distribution of  $\mathbf{x}$ :
 
$$p(\mathbf{x}|\mathbf{z}, \boldsymbol{\mu}) = \prod_{k=1}^K p(\mathbf{x}|\boldsymbol{\mu}_k)^{z_k}$$
  - Prior distribution for the latent variables
 
$$p(\mathbf{z}|\boldsymbol{\pi}) = \prod_{k=1}^K \pi_k^{z_k}$$
  - Again, we can verify that
 
$$p(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\pi}) = \sum_{\mathbf{z}} p(\mathbf{x}|\mathbf{z}, \boldsymbol{\mu}) p(\mathbf{z}|\boldsymbol{\pi}) = \sum_{k=1}^K \pi_k p(\mathbf{x}|\boldsymbol{\mu}_k)$$

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## Recap: General EM Algorithm

- Algorithm
  - Choose an initial setting for the parameters  $\boldsymbol{\theta}^{\text{old}}$
  - E-step: Evaluate  $p(\mathbf{Z}|\mathbf{X}, \boldsymbol{\theta}^{\text{old}})$**
  - M-step: Evaluate  $\boldsymbol{\theta}^{\text{new}}$  given by**

$$\boldsymbol{\theta}^{\text{new}} = \arg \max_{\boldsymbol{\theta}} Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}})$$

where

$$Q(\boldsymbol{\theta}, \boldsymbol{\theta}^{\text{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \boldsymbol{\theta}^{\text{old}}) \log p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\theta})$$
  - While not converged, let  $\boldsymbol{\theta}^{\text{old}} \leftarrow \boldsymbol{\theta}^{\text{new}}$  and return to step 2.

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## EM for Bernoulli Mixtures: E-Step

- Complete-data likelihood
 
$$p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\mu}, \boldsymbol{\pi}) = \prod_{n=1}^N \prod_{k=1}^K [\pi_k p(\mathbf{x}_n|\boldsymbol{\mu}_k)]^{z_{nk}}$$

$$= \prod_{n=1}^N \prod_{k=1}^K \left\{ \pi_k \prod_{i=1}^D \mu_{ki}^{z_{nk} x_{ni}} (1 - \mu_{ki})^{z_{nk} (1-x_{ni})} \right\}$$
- Posterior distribution of the latent variables  $\mathbf{Z}$ 

$$p(\mathbf{Z}|\mathbf{X}, \boldsymbol{\mu}, \boldsymbol{\pi}) = \frac{p(\mathbf{X}, \mathbf{Z}|\boldsymbol{\mu}, \boldsymbol{\pi})}{p(\mathbf{X}|\boldsymbol{\mu}, \boldsymbol{\pi})}$$

$$= \frac{\prod_{n=1}^N \prod_{k=1}^K [\pi_k p(\mathbf{x}_n|\boldsymbol{\mu}_k)]^{z_{nk}}}{\sum_{j=1}^K \pi_j p(\mathbf{x}_n|\boldsymbol{\mu}_j)^{z_{nk}}}$$

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## EM for Bernoulli Mixtures: E-Step

- E-Step
  - Evaluate the responsibilities
 
$$\gamma(z_{nk}) = \mathbb{E}[z_{nk}] = \frac{\sum_{z_{nk}} z_{nk} [\pi_k p(\mathbf{x}_n|\boldsymbol{\mu}_k)]^{z_{nk}}}{\sum_{j=1}^K \pi_j p(\mathbf{x}_n|\boldsymbol{\mu}_j)^{z_{nk}}}$$

$$= \frac{\pi_k p(\mathbf{x}_n|\boldsymbol{\mu}_k)}{\sum_{j=1}^K \pi_j p(\mathbf{x}_n|\boldsymbol{\mu}_j)}$$
  - Note: we again get the same form as for Gaussian mixtures
 
$$\gamma_j(\mathbf{x}_n) \leftarrow \frac{\pi_j \mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}{\sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{x}_n|\boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}$$

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## Recap: General EM Algorithm

- **Algorithm**
  1. Choose an initial setting for the parameters  $\theta^{\text{old}}$
  2. **E-step:** Evaluate  $p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}})$
  3. **M-step:** Evaluate  $\theta^{\text{new}}$  given by
 

$$\theta^{\text{new}} = \arg \max_{\theta} Q(\theta, \theta^{\text{old}})$$

where

$$Q(\theta, \theta^{\text{old}}) = \sum_{\mathbf{Z}} p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}}) \log p(\mathbf{X}, \mathbf{Z}|\theta)$$
  4. While not converged, let  $\theta^{\text{old}} \leftarrow \theta^{\text{new}}$  and return to step 2.

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## EM for Bernoulli Mixtures: M-Step

- **Complete-data log-likelihood**

$$\log p(\mathbf{X}, \mathbf{Z}|\mu, \pi) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \{ \log \pi_k + [x_{ni} \log \mu_{ki} + (1 - x_{ni}) \log(1 - \mu_{ki})] \}$$
- **Expectation w.r.t. the posterior distribution of  $\mathbf{Z}$** 

$$\mathbb{E}_{\mathbf{Z}}[\log p(\mathbf{X}, \mathbf{Z}|\mu, \pi)] = \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \{ \log \pi_k + [x_{ni} \log \mu_{ki} + (1 - x_{ni}) \log(1 - \mu_{ki})] \}$$

$Q(\theta, \theta^{\text{old}})$

where  $\gamma(z_{nk}) = \mathbb{E}[z_{nk}]$  are again the responsibilities for each  $\mathbf{x}_n$ .

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## EM for Bernoulli Mixtures: M-Step

- **Remark**
  - The  $\gamma(z_{nk})$  only occur in two forms in the expectation:
 
$$N_k = \sum_{n=1}^N \gamma(z_{nk})$$

$$\bar{\mathbf{x}}_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) \mathbf{x}_n$$
- **Interpretation**
  - $N_k$  is the effective number of data points associated with component  $k$ .
  - $\bar{\mathbf{x}}_k$  is the responsibility-weighted mean of the data points softly assigned to component  $k$ .

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## EM for Bernoulli Mixtures: M-Step

- **M-Step**
  - Maximize the expected complete-data log-likelihood w.r.t the parameter  $\mu_k$ .
$$\frac{\partial}{\partial \mu_k} \mathbb{E}_{\mathbf{Z}}[\log p(\mathbf{X}, \mathbf{Z}|\mu, \pi)] = \frac{\partial}{\partial \mu_k} \sum_{n=1}^N \sum_{k=1}^K \gamma(z_{nk}) \{ \log \pi_k + [x_n \log \mu_k + (1 - x_n) \log(1 - \mu_k)] \}$$

$$= \frac{1}{\mu_k} \sum_{n=1}^N \gamma(z_{nk}) x_n - \frac{1}{1 - \mu_k} \sum_{n=1}^N \gamma(z_{nk}) (1 - x_n) \stackrel{!}{=} 0$$

$$\vdots$$

$$\mu_k = \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) x_n = \bar{\mathbf{x}}_k$$

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## EM for Bernoulli Mixtures: M-Step

- **M-Step**
  - Maximize the expected complete-data log-likelihood w.r.t the parameter  $\pi_k$  under the **constraint**  $\sum_k \pi_k = 1$ .
  - Solution with Lagrange multiplier  $\lambda$ 

$$\arg \max_{\pi_k} \mathbb{E}_{\mathbf{Z}}[\log p(\mathbf{X}, \mathbf{Z}|\mu, \pi)] + \lambda \left( \sum_{k=1}^K \pi_k - 1 \right)$$

$$\pi_k = \frac{N_k}{N}$$

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## Discussion




- **Comparison with Gaussian mixtures**
  - In contrast to Gaussian mixtures, there are no singularities in which the likelihood goes to infinity.
  - This follows from the property of Bernoulli distributions that
 
$$0 \leq p(\mathbf{x}_n | \mu_k) \leq 1$$
  - However, there are still problem cases when  $\mu_{ki}$  becomes 0 or 1
 
$$\mathbb{E}_{\mathbf{Z}}[\log p(\mathbf{X}, \mathbf{Z}|\mu, \pi)] = \dots [x_{ni} \log \mu_{ki} + (1 - x_{ni}) \log(1 - \mu_{ki})]$$
 $\Rightarrow$  Need to enforce a range [MIN\_VAL, 1-MIN\_VAL] for either  $\mu_{ki}$  or  $\gamma$ .
- **General remarks**
  - Bernoulli mixtures are used in practice in order to represent binary data.
  - The resulting model is also known as **latent class analysis**.

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### Example: Handwritten Digit Recognition

- Binarized digit data (examples from set of 600 digits)
 
- Means of a 3-component Bernoulli mixture (10 EM iter.)
 
- Comparison: ML result of single multivariate Bernoulli distribution
 

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### Topics of This Lecture

- The EM algorithm in general
  - Recap: General EM
  - Example: Mixtures of Bernoulli distributions
  - Monte Carlo EM
- Bayesian Mixture Models
  - Towards a full Bayesian treatment
  - Dirichlet priors
  - Finite mixtures
  - Infinite mixtures
  - Approximate inference (only as supplementary material)

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### Monte Carlo EM

- EM procedure
  - M-step: Maximize expectation of complete-data log-likelihood
 
$$Q(\theta, \theta^{\text{old}}) = \int p(\mathbf{Z}|\mathbf{X}, \theta^{\text{old}}) \log p(\mathbf{X}, \mathbf{Z}|\theta) d\mathbf{Z}$$
  - For more complex models, we may not be able to compute this analytically anymore...
- Idea
  - Use sampling to approximate this integral by a finite sum over samples  $\{\mathbf{Z}^{(l)}\}$  drawn from the current estimate of the posterior
 
$$Q(\theta, \theta^{\text{old}}) \sim \frac{1}{L} \sum_{l=1}^L \log p(\mathbf{X}, \mathbf{Z}^{(l)}|\theta^{\text{old}})$$
  - This procedure is called the **Monte Carlo EM algorithm**.

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### Topics of This Lecture

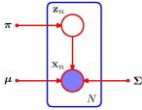
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### Towards a Full Bayesian Treatment...

- Mixture models
  - We have discussed mixture distributions with  $K$  components
 
$$p(\mathbf{X}|\theta) = \sum_{\mathbf{Z}} p(\mathbf{X}, \mathbf{Z}|\theta)$$

  - So far, we have derived the ML estimates  $\Rightarrow$  EM
  - Introduced a prior  $p(\theta)$  over parameters  $\Rightarrow$  MAP-EM
  - One question remains open: how to set  $K$ ?  $\Rightarrow$  Let's also set a prior on the number of components...

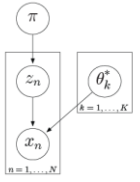
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### Bayesian Mixture Models

- Let's be Bayesian about mixture models
  - Place priors over our parameters
  - Again, introduce variable  $z_n$  as indicator which component data point  $x_n$  belongs to.
 
$$z_n | \pi \sim \text{Multinomial}(\pi)$$

$$x_n | z_n = k, \mu, \Sigma \sim \mathcal{N}(\mu_k, \Sigma_k)$$
  - This is similar to the graphical model we've used before, but now the  $\pi$  and  $\theta_k = (\mu_k, \Sigma_k)$  are also treated as random variables.
  - What would be suitable priors for them?

Slide inspired by Yee Whye Teh B. Leibe

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## Bayesian Mixture Models

- Let's be Bayesian about mixture models
  - Place priors over our parameters
  - Again, introduce variable  $z_n$  as indicator which component data point  $x_n$  belongs to.
 
$$z_n | \pi \sim \text{Multinomial}(\pi)$$

$$x_n | z_n = k, \mu, \Sigma \sim \mathcal{N}(\mu_k, \Sigma_k)$$
  - Introduce **conjugate priors** over parameters
 
$$\pi \sim \text{Dirichlet}\left(\frac{\alpha}{K}, \dots, \frac{\alpha}{K}\right)$$

$$\mu_k, \Sigma_k \sim H = \mathcal{N} - \mathcal{IW}(0, s, d, \phi)$$

**"Normal - Inverse Wishart"**

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Slide inspired by Yee Whye Teh

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## Bayesian Mixture Models

- Full Bayesian Treatment
  - Given a dataset, we are interested in the cluster assignments
 
$$p(\mathbf{Z} | \mathbf{X}) = \frac{p(\mathbf{X} | \mathbf{Z}) p(\mathbf{Z})}{\sum_{\mathbf{Z}} p(\mathbf{X} | \mathbf{Z}) p(\mathbf{Z})}$$

where the likelihood is obtained by marginalizing over the parameters  $\theta$

$$p(\mathbf{X} | \mathbf{Z}) = \int p(\mathbf{X} | \mathbf{Z}, \theta) p(\theta) d\theta$$

$$= \int \prod_{n=1}^N \prod_{k=1}^K p(x_n | z_n, \theta_k) p(\theta_k | H) d\theta$$
  - The posterior over assignments is intractable!
    - Denominator requires summing over all possible partitions of the data into  $K$  groups!
    - ⇒ Need efficient approximate inference methods to solve this...

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## Bayesian Mixture Models

- Let's examine this model more closely
  - Role of Dirichlet priors?
  - How can we perform efficient inference?
  - What happens when  $K$  goes to infinity?
- This will lead us to an interesting class of models...
  - Dirichlet Processes
  - Possible to express infinite mixture distributions with their help
  - Clustering that automatically adapts the number of clusters to the data and *dynamically creates new clusters on-the-fly*.

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## Sneak Preview: Dirichlet Process MoG

Samples drawn from DP mixture

⇒ More structure appears as more points are drawn

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## Recap: The Dirichlet Distribution

- Dirichlet Distribution
  - Conjugate prior for the Categorical and the Multinomial distrib.
$$\text{Dir}(\mu | \alpha) = \frac{\Gamma(\alpha_0)}{\Gamma(\alpha_1) \dots \Gamma(\alpha_K)} \prod_{k=1}^K \mu_k^{\alpha_k - 1} \quad \text{with} \quad \alpha_0 = \sum_{k=1}^K \alpha_k$$
- Symmetric version (with concentration parameter  $\alpha$ )
 
$$\text{Dir}(\mu | \alpha) = \frac{\Gamma(\alpha)^K}{\Gamma(\alpha/K)^K} \prod_{k=1}^K \mu_k^{\alpha/K - 1}$$
- Properties (symmetric version)
 
$$\mathbb{E}[\mu_k] = \frac{\alpha_k}{\alpha_0} = \frac{1}{K}$$

$$\text{var}[\mu_k] = \frac{\alpha_k(\alpha_0 - \alpha_k)}{\alpha_0^2(\alpha_0 + 1)} = \frac{K-1}{K^2(\alpha+1)}$$

$$\text{cov}[\mu_j, \mu_k] = -\frac{\alpha_j \alpha_k}{\alpha_0^2(\alpha_0 + 1)} = -\frac{1}{K^2(\alpha+1)}$$

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Image source: C. Bishop, 2006

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## Dirichlet Samples

Dir( $\theta$  | 0.1, 0.1, 0.1, 0.1, 0.1)      Dir( $\theta$  | 1.0, 1.0, 1.0, 1.0, 1.0)

- Effect of concentration parameter  $\alpha$ 
  - Controls sparsity of the resulting samples

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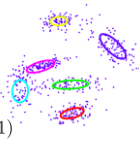
Slide credit: Erik Sudderth

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### Mixture Model with Dirichlet Priors

- Finite mixture of  $K$  components

$$p(\mathbf{x}_n | \theta) = \sum_{k=1}^K \pi_k p(\mathbf{x}_n | \theta_k)$$

$$= \sum_{k=1}^K p(z_{nk} = 1 | \pi_k) p(\mathbf{x}_n | \theta_k, z_{nk} = 1)$$


- The distribution of latent variables  $\mathbf{z}_n$  given  $\pi$  is multinomial

$$p(\mathbf{z} | \pi) = \prod_{k=1}^K \pi_k^{N_k}, \quad N_k \stackrel{\text{def}}{=} \sum_{n=1}^N z_{nk}$$

- Assume mixing proportions have a given symmetric conjugate Dirichlet prior

$$p(\pi | \alpha) = \frac{\Gamma(\alpha)^K}{\Gamma(\alpha/K)^K} \prod_{k=1}^K \pi_k^{\alpha/K - 1}$$

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### Mixture Model with Dirichlet Priors

- Integrating out the mixing proportions  $\pi$ :

$$p(\mathbf{z} | \alpha) = \int p(\mathbf{z} | \pi) p(\pi | \alpha) d\pi$$

$$= \int \prod_{k=1}^K \pi_k^{N_k} \cdot \frac{\Gamma(\alpha)^K}{\Gamma(\alpha/K)^K} \prod_{k=1}^K \pi_k^{\alpha/K - 1} d\pi$$

$$= \int \frac{\Gamma(\alpha)^K}{\Gamma(\alpha/K)^K} \prod_{k=1}^K \pi_k^{N_k + \alpha/K - 1} d\pi$$

- This is again a Dirichlet distribution (reason for conjugate priors)

$$= \frac{\Gamma(\alpha)^K \prod_{k=1}^K \Gamma(N_k + \alpha/K)}{\Gamma(N + \alpha)^K} \int \frac{\Gamma(N + \alpha)}{\prod_{k=1}^K \Gamma(N_k + \alpha/K)} \prod_{k=1}^K \pi_k^{N_k + \alpha/K - 1} d\pi$$

Completed Dirichlet form  $\rightarrow$  integrates to 1

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### Mixture Models with Dirichlet Priors

- Integrating out the mixing proportions  $\pi$  (cont'd)

$$p(\mathbf{z} | \alpha) = \frac{\Gamma(\alpha)^K \prod_{k=1}^K \Gamma(N_k + \alpha/K)}{\Gamma(\alpha/K)^K \Gamma(N + \alpha)^K}$$

$$= \frac{\Gamma(\alpha)^K}{\Gamma(N + \alpha)^K} \prod_{k=1}^K \frac{\Gamma(N_k + \alpha/K)}{\Gamma(\alpha/K)}$$

- Conditional probabilities

  - Let's examine the conditional of  $\mathbf{z}_n$  given all other variables

$$p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) = \frac{p(z_{nk} = 1, \mathbf{z}_{-n} | \alpha)}{p(\mathbf{z}_{-n} | \alpha)}$$

where  $\mathbf{z}_{-n}$  denotes all indices except  $n$ .

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### Mixture Models with Dirichlet Priors

- Conditional probabilities

$$p(\mathbf{z} | \alpha) = \frac{\Gamma(\alpha)^K}{\Gamma(N + \alpha)^K} \prod_{k=1}^K \frac{\Gamma(N_k + \alpha/K)}{\Gamma(\alpha/K)}$$

$$p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) = \frac{p(z_{nk} = 1, \mathbf{z}_{-n} | \alpha)}{p(\mathbf{z}_{-n} | \alpha)}$$

$$= \frac{\frac{\Gamma(\alpha)^K}{\Gamma(N + \alpha)^K} \frac{\Gamma(N_k + \alpha/K)}{\Gamma(\alpha/K)} \prod_{j=1, j \neq k}^K \frac{\Gamma(N_j + \alpha/K)}{\Gamma(\alpha/K)}}{\frac{\Gamma(\alpha)^K}{\Gamma(N - n + \alpha)^K} \prod_{j=1, j \neq k}^K \frac{\Gamma(N_j + \alpha/K)}{\Gamma(\alpha/K)}}$$

$$= \frac{\Gamma(N - n + \alpha)}{\Gamma(N + \alpha)} \frac{\Gamma(N_k + \alpha/K)}{\Gamma(N - n, k + \alpha/K)}$$

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### Mixture Models with Dirichlet Priors

- Conditional probabilities

$$p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) = \frac{p(z_{nk} = 1, \mathbf{z}_{-n} | \alpha)}{p(\mathbf{z}_{-n} | \alpha)}$$

$$= \frac{\frac{\Gamma(\alpha)^K}{\Gamma(N + \alpha)^K} \frac{\Gamma(N_k + \alpha/K)}{\Gamma(\alpha/K)} \prod_{j=1, j \neq k}^K \frac{\Gamma(N_j + \alpha/K)}{\Gamma(\alpha/K)}}{\frac{\Gamma(\alpha)^K}{\Gamma(N - n + \alpha)^K} \prod_{j=1, j \neq k}^K \frac{\Gamma(N_j + \alpha/K)}{\Gamma(\alpha/K)}}$$

$$= \frac{\Gamma(N - n + \alpha)}{\Gamma(N + \alpha)} \frac{\Gamma(N_k + \alpha/K)}{\Gamma(N - n, k + \alpha/K)}$$

$$= \frac{1}{N - 1 + \alpha} \frac{N - n, k + \alpha/K}{1}$$

$$= \frac{N - n, k + \alpha/K}{N - 1 + \alpha}$$

$\Gamma(n + 1) = n\Gamma(n)$

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### Finite Dirichlet Mixture Models

- Conditional probabilities: Finite  $K$

$$p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) = \frac{N - n, k + \alpha/K}{N - 1 + \alpha}, \quad N - n, k \stackrel{\text{def}}{=} \sum_{i=1, i \neq n}^N z_{ik}$$

- This is a very interesting result. Why?
  - We directly get a numerical probability, no distribution.
  - The probability of joining a cluster mainly depends on the number of existing entries in a cluster.
    - $\Rightarrow$  The **more populous** a class is, the more likely it is to be joined!
  - In addition, we have a **base probability** of also joining as-yet empty clusters.
  - This result can be directly used in Gibbs Sampling...

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## Infinite Dirichlet Mixture Models

- Conditional probabilities: Finite  $K$ 

$$p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) = \frac{N_{-n,k} + \alpha/K}{N - 1 + \alpha}, \quad N_{-n,k} \stackrel{\text{def}}{=} \sum_{i=1, i \neq n}^N z_{ik}$$
- Conditional probabilities: Infinite  $K$ 
  - Taking the limit as  $K \rightarrow \infty$  yields the conditionals
 
$$p(z_{nk} = 1 | \mathbf{z}_{-n}, \alpha) = \begin{cases} \frac{N_{-n,k}}{N-1+\alpha} & \text{if } k \text{ represented} \\ \frac{\alpha}{N-1+\alpha} & \text{if all } k \text{ not represented} \end{cases}$$
  - Left-over mass  $\alpha \Rightarrow$  countably infinite number of indicator settings

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## Discussion

- Infinite Mixture Models
  - What we have just seen is a first example of a **Dirichlet Process**.
  - DPs allow us to work with models that have an infinite number of components.
  - This will raise a number of issues
    - How to represent infinitely many parameters?
    - How to deal with permutations of the class labels?
    - How to control the effective size of the model?
    - How to perform efficient inference?
  - ⇒ More background needed here!
  - DPs are a very interesting class of models, but would take us too far here.
  - If you're interested in learning more about them, take a look at the Advanced ML slides from Winter 2012.

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## Next Lecture...



Deep Learning


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## References and Further Reading

- More information about EM estimation is available in Chapter 9 of Bishop's book (recommendable to read).
 

Christopher M. Bishop  
 Pattern Recognition and Machine Learning  
 Springer, 2006


- Additional information
  - Original EM paper:
    - A.P. Dempster, N.M. Laird, D.B. Rubin, „Maximum-Likelihood from incomplete data via EM algorithm”, In Journal Royal Statistical Society, Series B. Vol 39, 1977
  - EM tutorial:
    - J.A. Bilmes, “A Gentle Tutorial of the EM Algorithm and its Application to Parameter Estimation for Gaussian Mixture and Hidden Markov Models”, TR-97-021, ICSI, U.C. Berkeley, CA, USA

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