

# Computer Vision 2

## WS 2018/19

### Part 17 – CNNs for Video Analysis I

15.01.2019

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RWTH Aachen University, Computer Vision Group

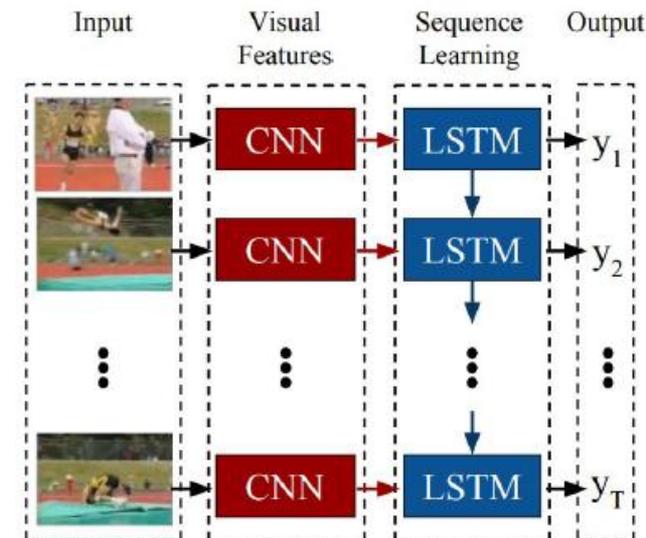
<http://www.vision.rwth-aachen.de>



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# Course Outline

- Single-Object Tracking
- Bayesian Filtering
- Multi-Object Tracking
- Visual Odometry
- Visual SLAM & 3D Reconstruction
  - Online SLAM methods
  - Full SLAM methods
- Deep Learning for Video Analysis
  - CNNs for video analysis
  - Optical flow
  - Video object segmentation

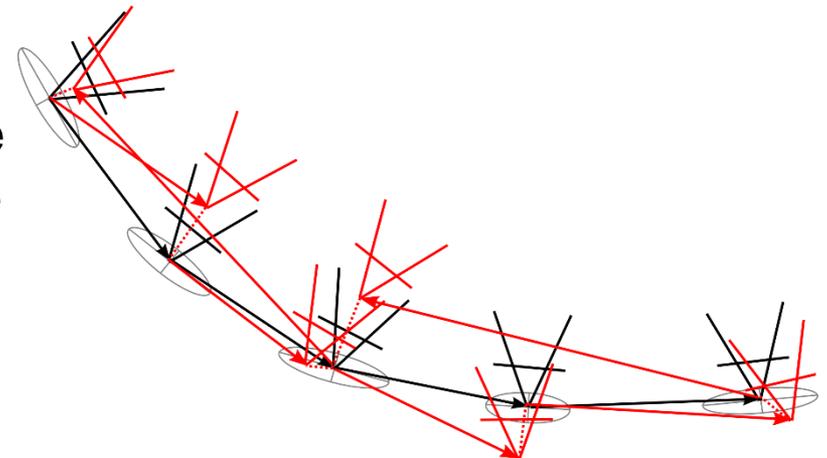
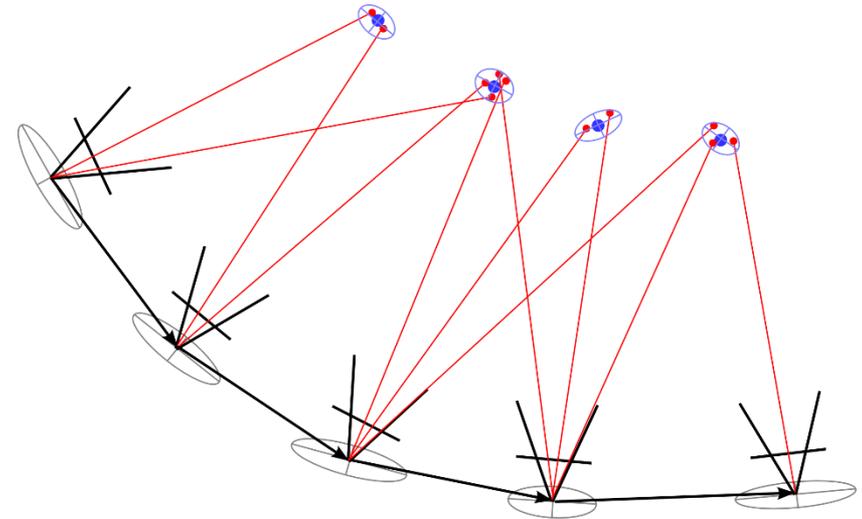


# Topics of This Lecture

- **Recap: Full SLAM methods**
- **CNNs for Video Analysis**
  - Motivation
  - Example: Video classification
- **CNN + RNN**
  - RNN, LSTM
  - Example: Video captioning
- **Matching and correspondence estimation**
  - Metric learning
  - Correspondence networks

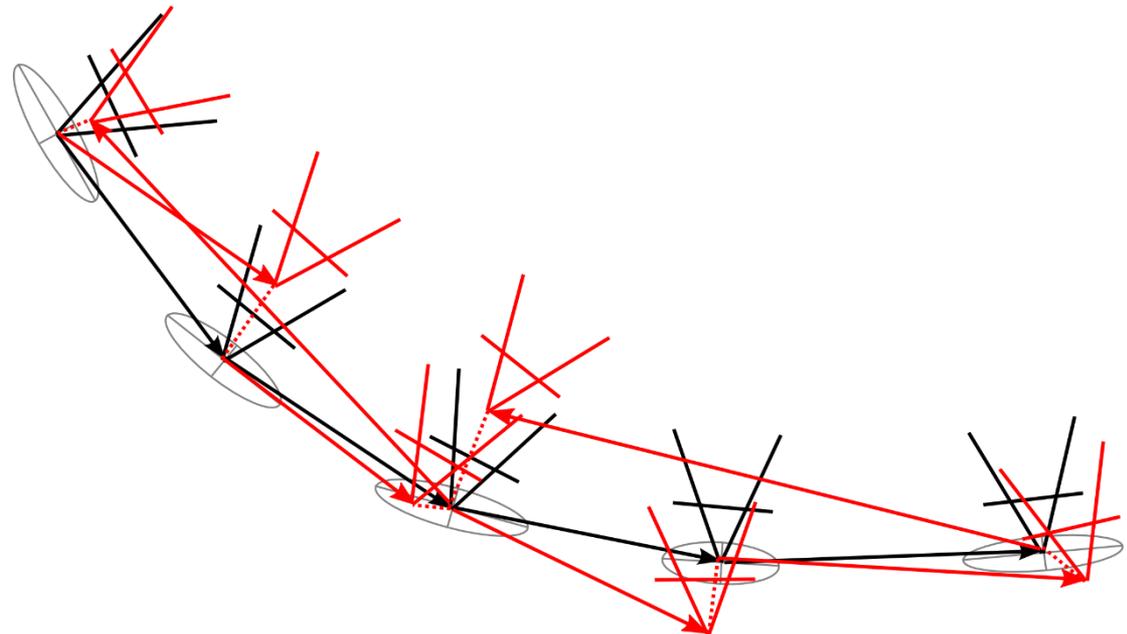
# Recap: Full SLAM Approaches

- **SLAM graph optimization:**
  - Joint optimization for poses and map elements from image observations of map elements and control inputs
- **Pose graph optimization:**
  - Optimization of poses from relative pose constraints deduced from the image observations
  - Map recovered from the optimized poses



# Pose Graph Optimization

- Optimization of poses
  - From relative pose constraints deduced from the image observations
  - Map recovered from the optimized poses
- Deduce relative constraints between poses from image observations, e.g.,
  - 8-point algorithm
  - Direct image alignment



## Dense Visual SLAM for RGB-D Cameras

Christian Kerl, Jürgen Sturm,  
Daniel Cremers



Computer Vision and Pattern Recognition Group  
Department of Computer Science  
Technical University of Munich



Kerl et al., [Dense Visual SLAM for RGB-D Cameras](#), IROS 2013

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# Video Analysis with CNNs

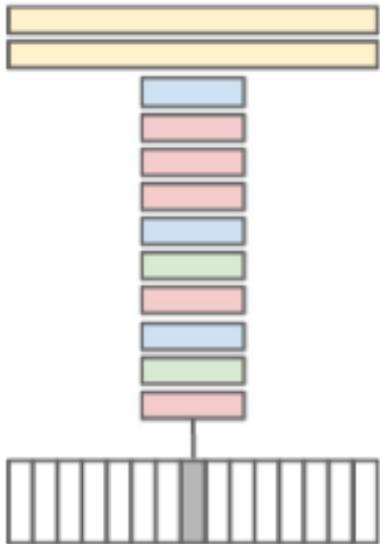


- Modeling perspective
  - What **architecture** to use to best capture temporal patterns?
- Computational perspective
  - Video processing is expensive!
  - How to reduce **computation cost** without sacrificing accuracy

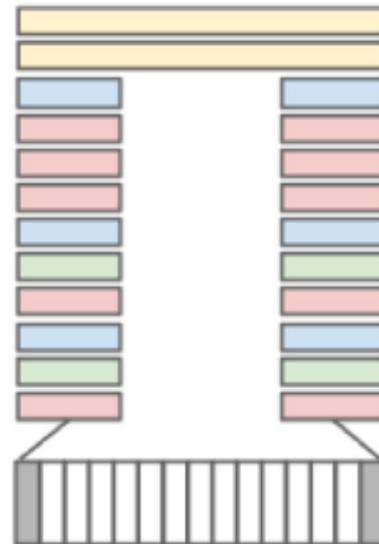
# Large-Scale Video Classification with CNNs

- Architecture
  - Different ways to fuse features from multiple frames

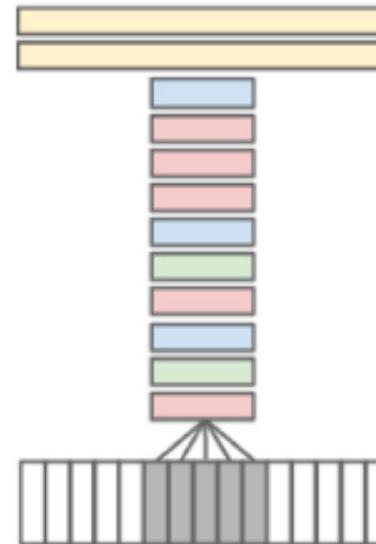
## Single Frame



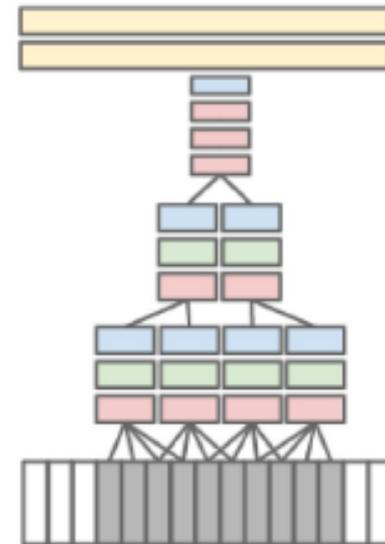
## Late Fusion



## Early Fusion



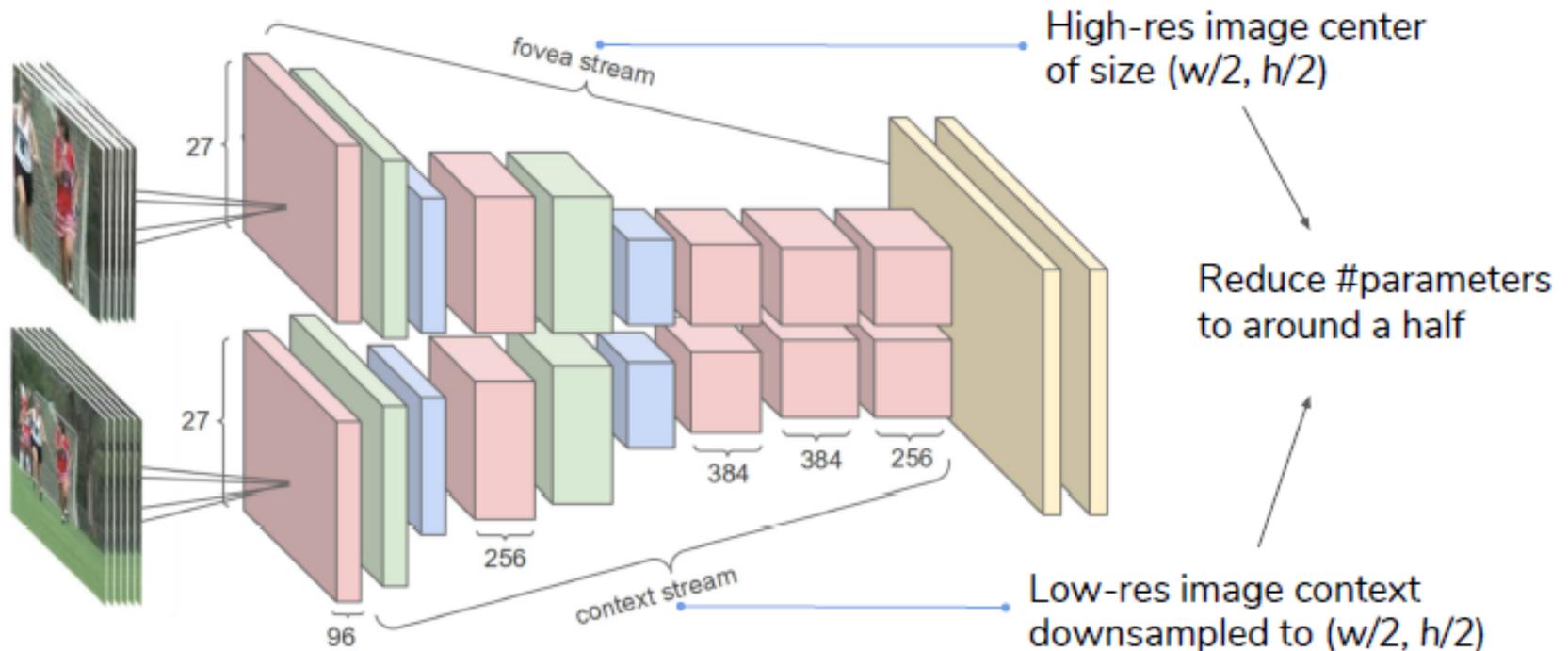
## Slow Fusion



 Conv layer     Norm layer     Pooling layer

# Large-Scale Video Classification with CNNs

- Computational cost
  - Reduce spatial dimension to reduce model complexity
  - Multi-resolution: low-res context + high-res foveate

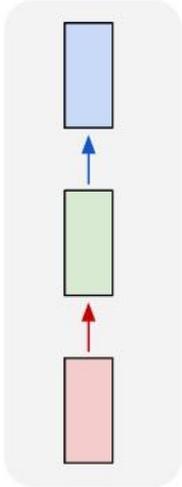


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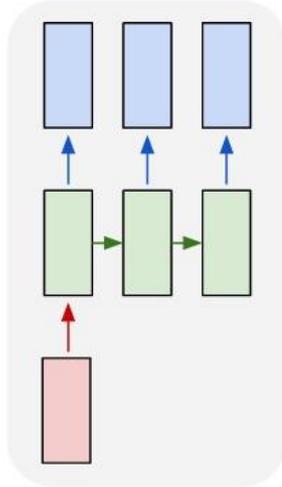
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# Recap: Recurrent Networks

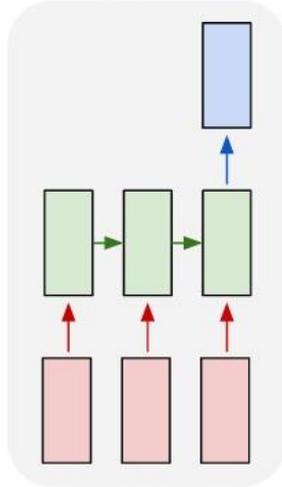
one to one



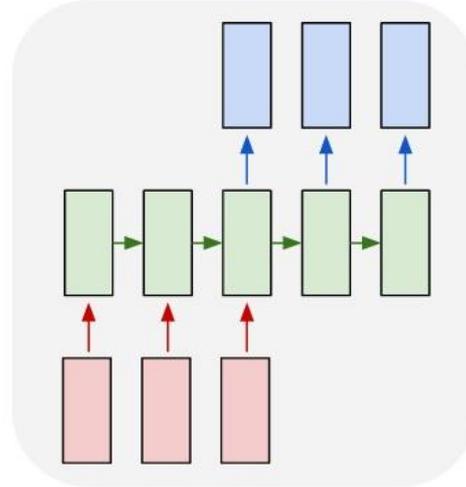
one to many



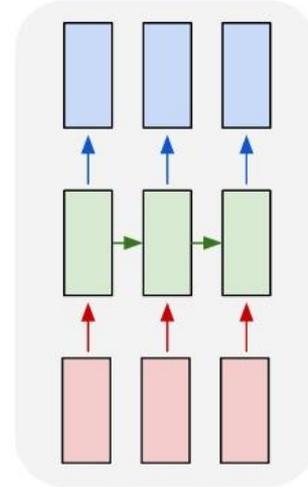
many to one



many to many



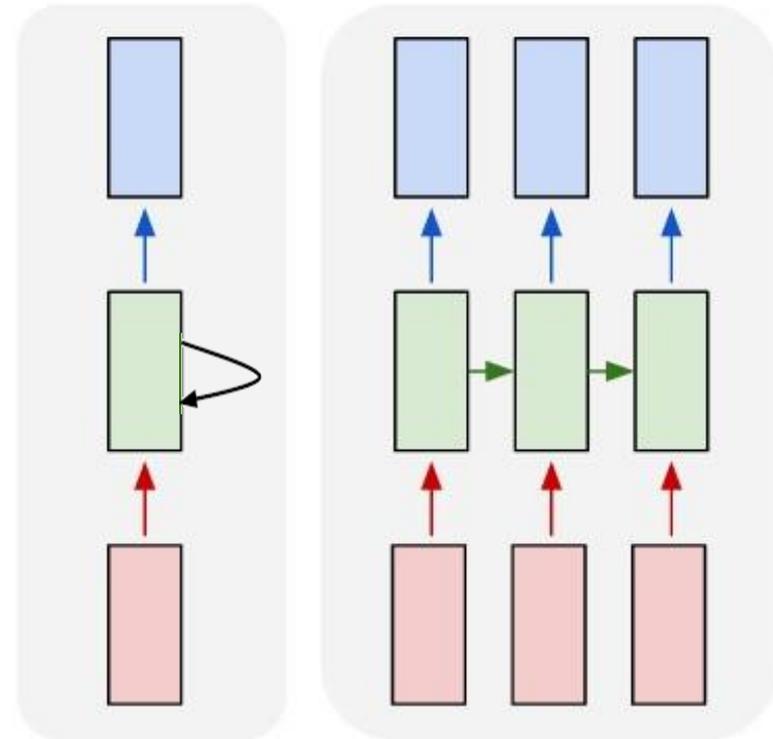
many to many



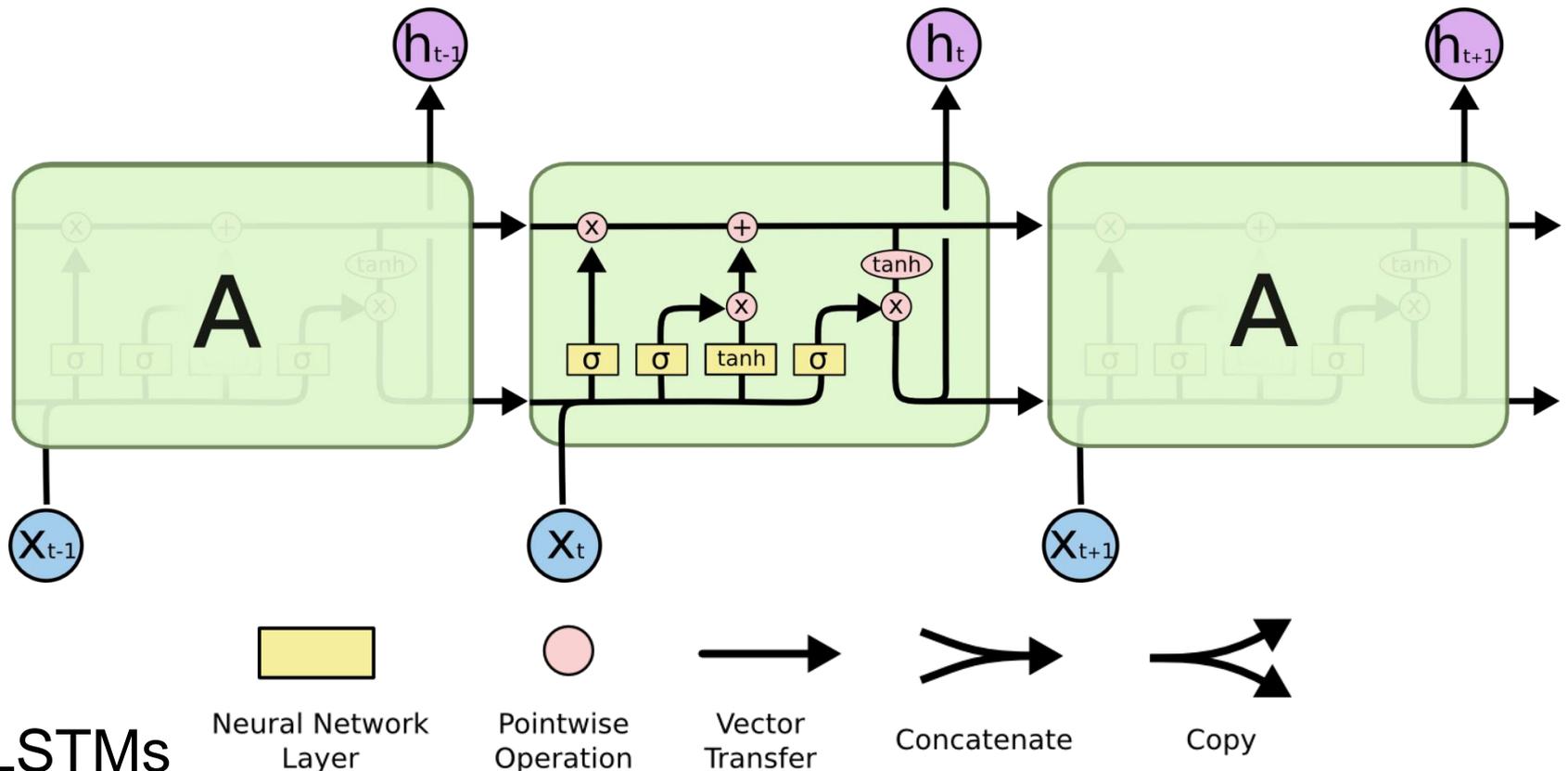
- Feed-forward networks
  - Simple neural network structure: 1-to-1 mapping of inputs to outputs
- Recurrent Neural Networks
  - Generalize this to arbitrary mappings

# Recap: RNNs

- RNNs are regular NNs whose hidden units have additional forward connections over time.
  - You can **unroll** them to create a network that extends over time.
  - When you do this, keep in mind that the weights for the hidden units are shared between temporal layers.



# Extension: Long Short-Term Memory (LSTM)

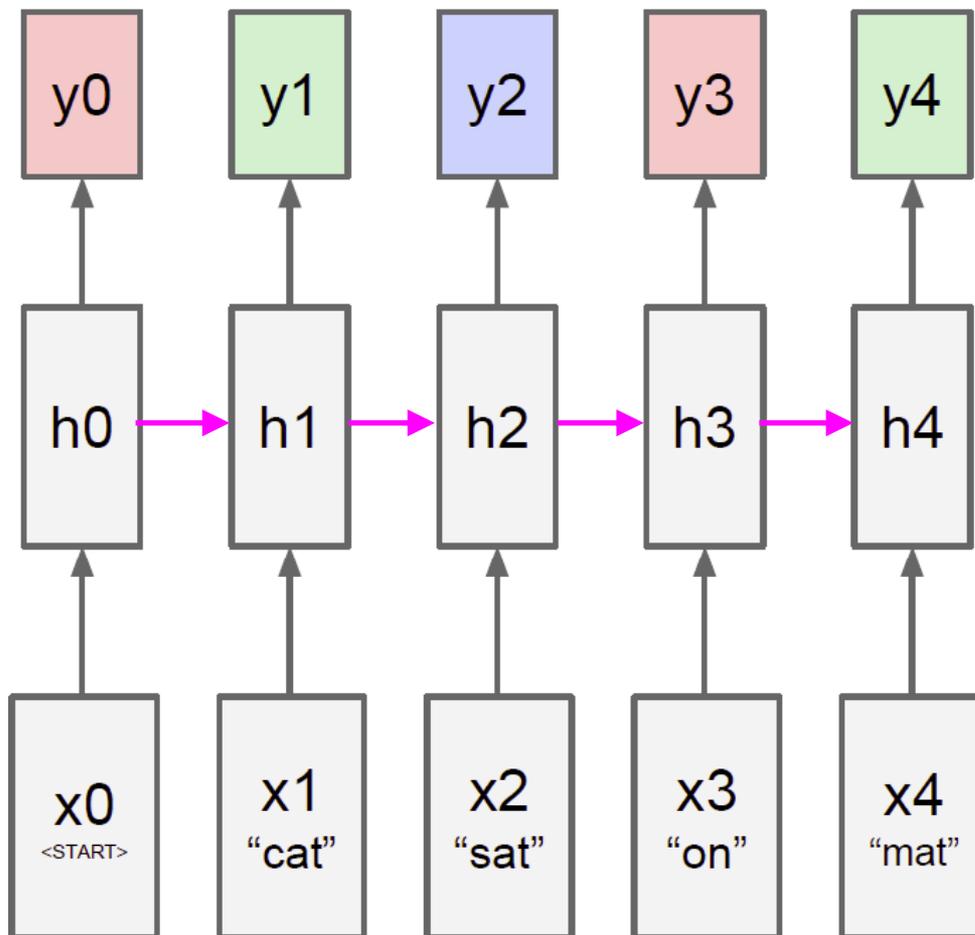


- **LSTMs**

- Inspired by the design of memory cells
- Each module has 4 layers, interacting in a special way.
- Effect: LSTMs can learn longer dependencies (~100 steps) than RNNs

# Recap: RNNs for Text Generation

- RNN for text generation



10,001D class scores  
(Softmax over 10k  
words and a special  
<END> token)

$$\mathbf{y}_4 = \mathbf{W}_{hy} \mathbf{h}_4$$

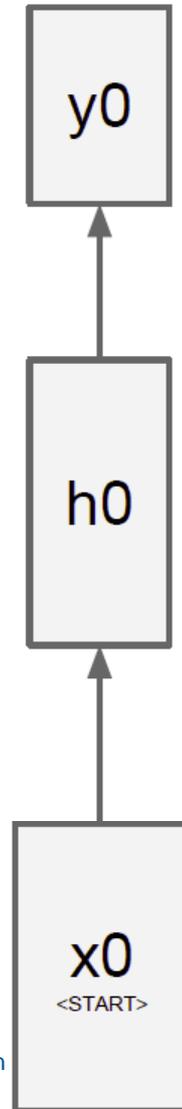
Hidden layer  
(e.g., 500D vectors)

$$\mathbf{h}_4 = \max \{0, \mathbf{W}_{xh} \mathbf{x}_4 + \mathbf{W}_{hh} \mathbf{h}_3\}$$

# Recap: RNNs for Text Generation

- Training this on a lot of sentences would give us a language model.
- I.e., a way to predict

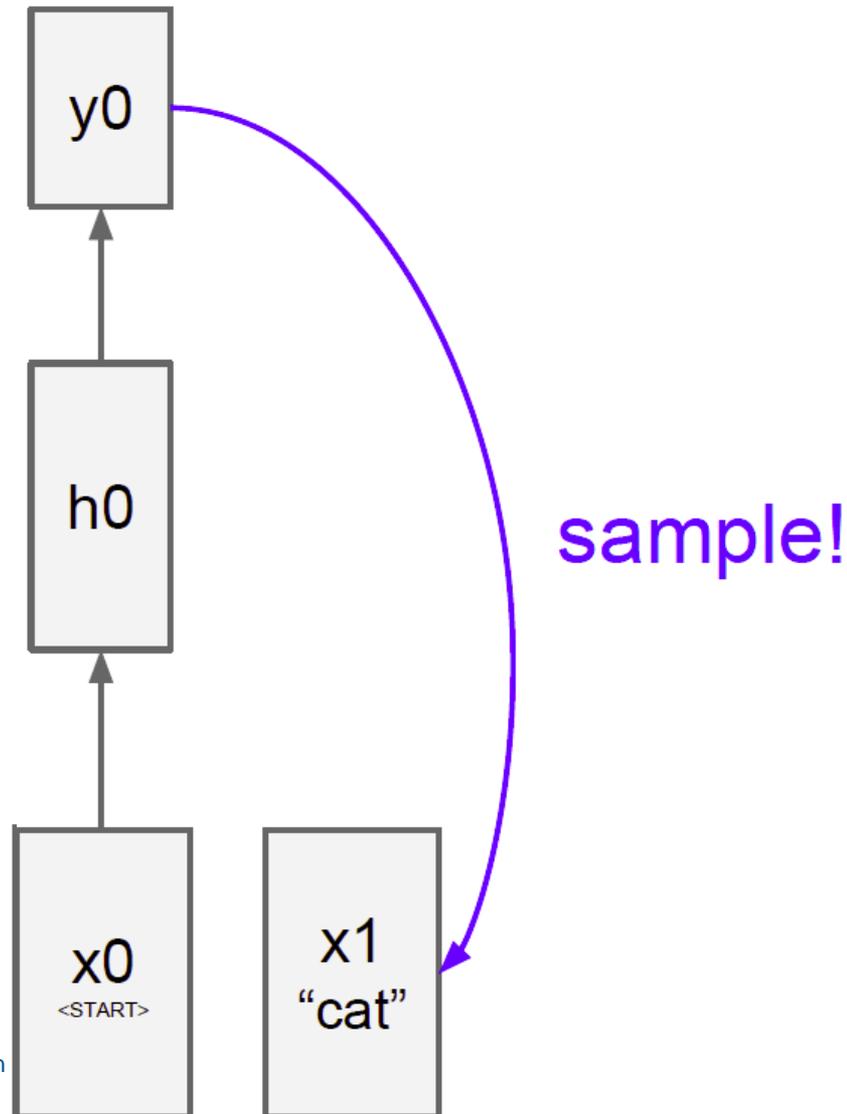
$$p(\textit{next word} \mid \textit{previous words})$$



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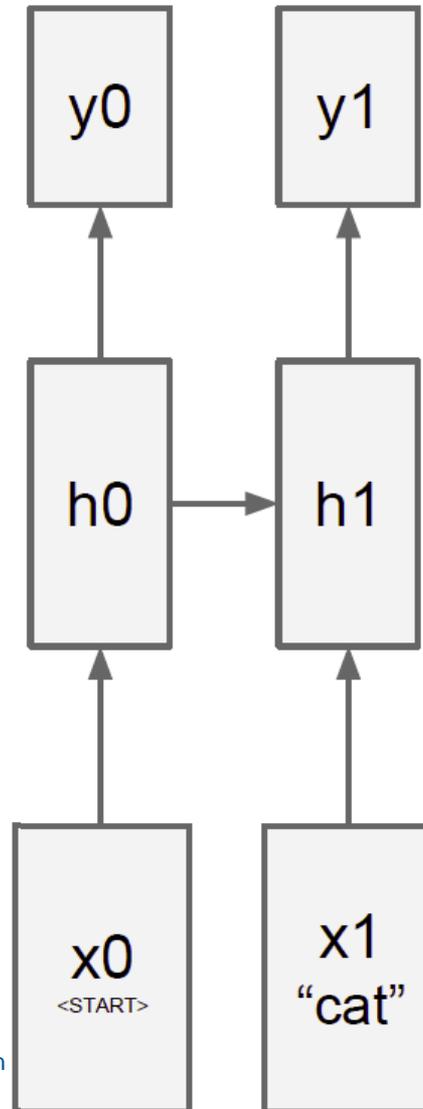
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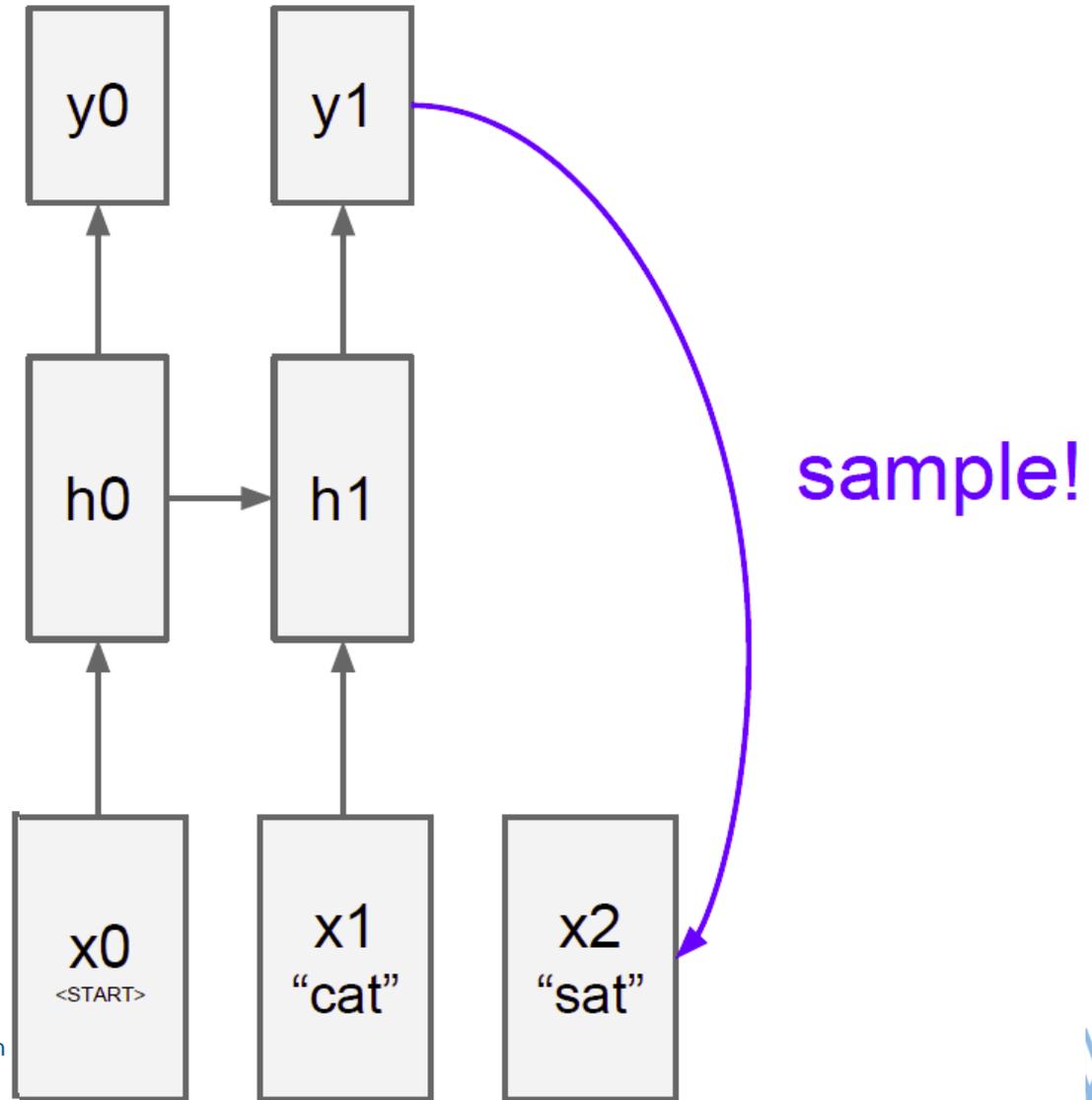
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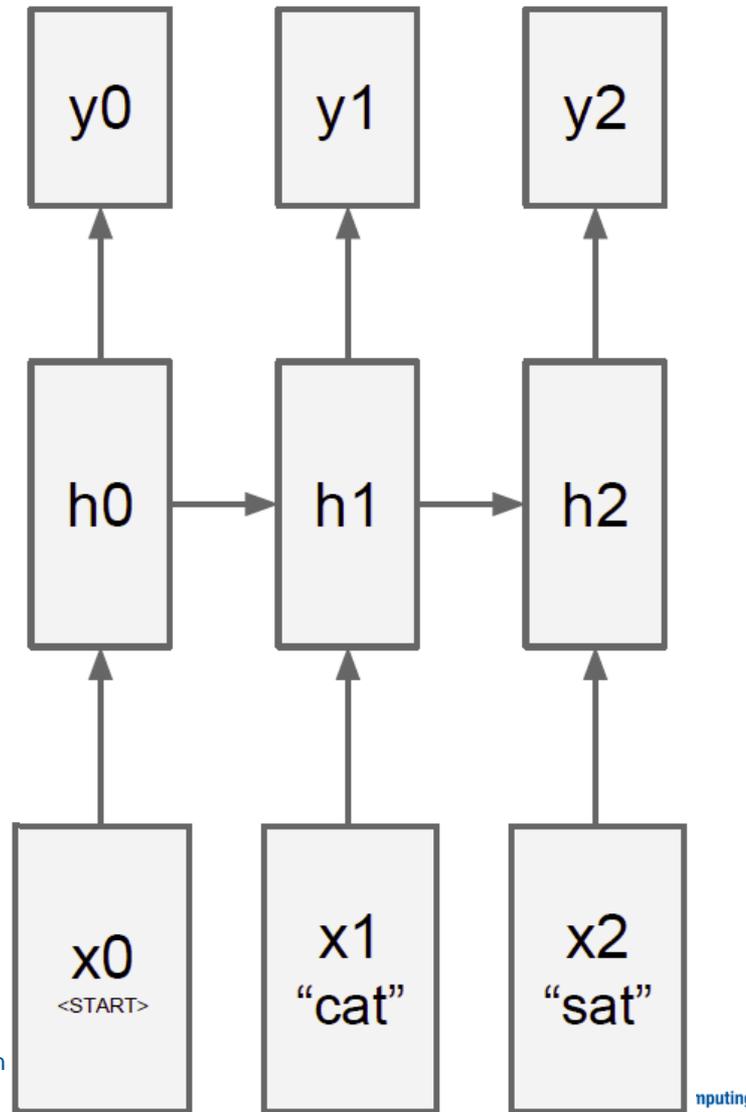
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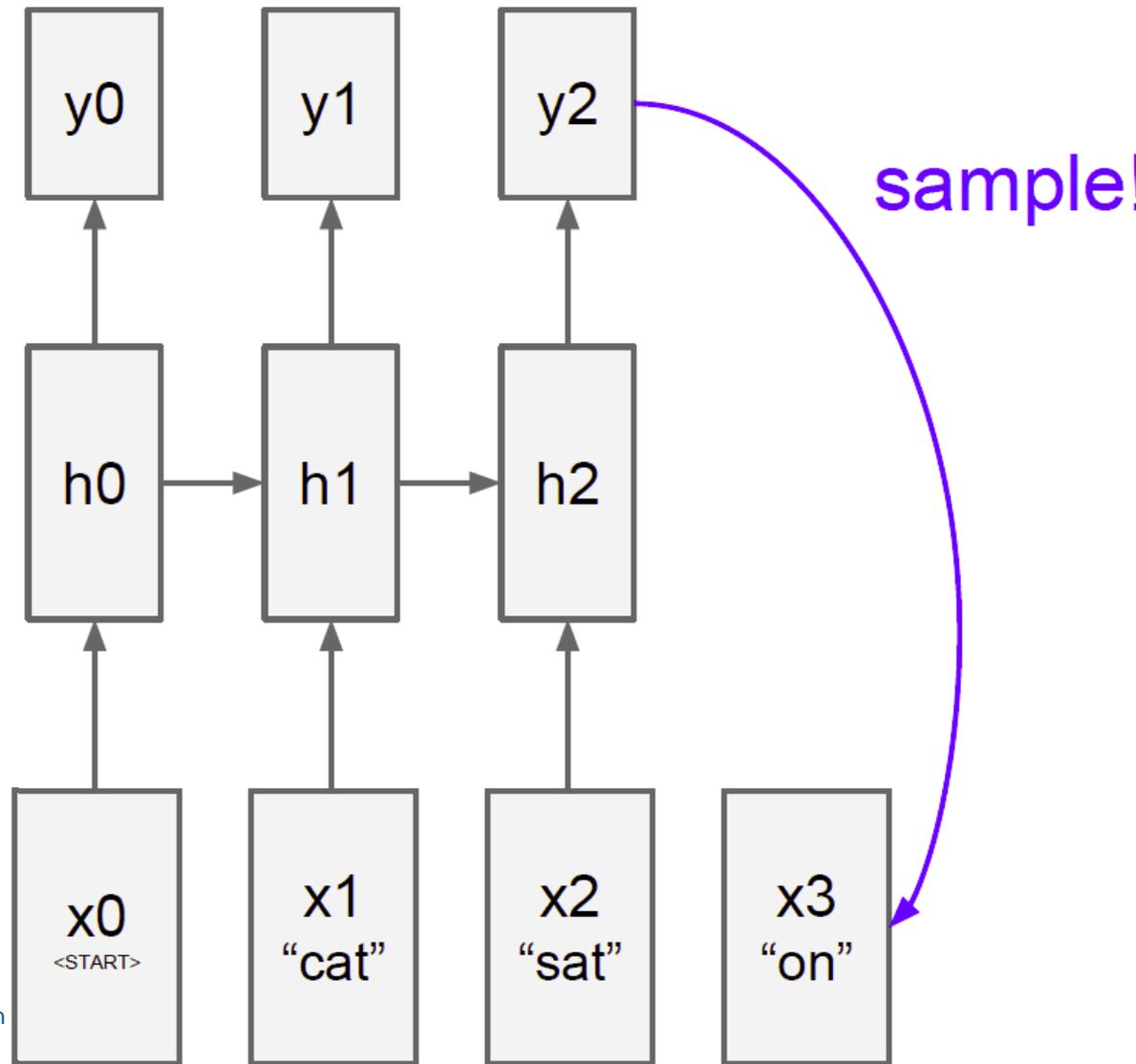
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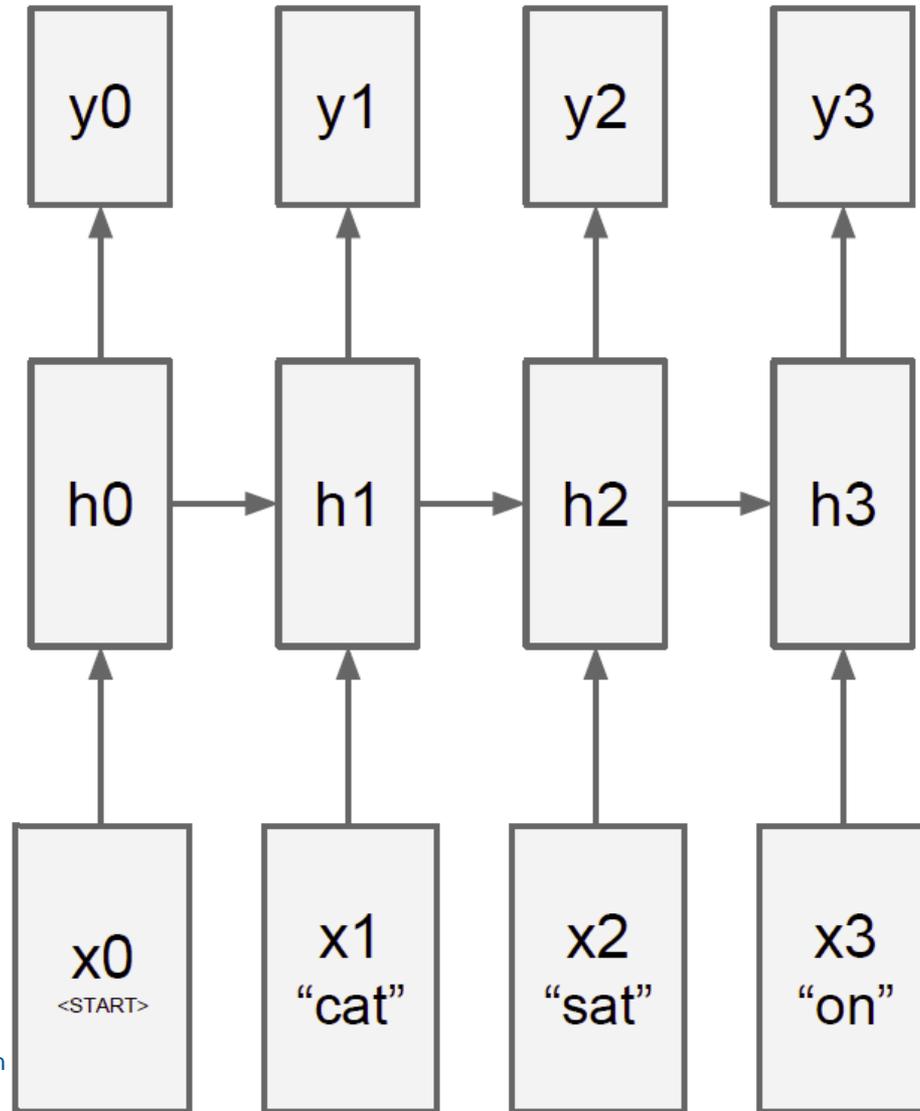
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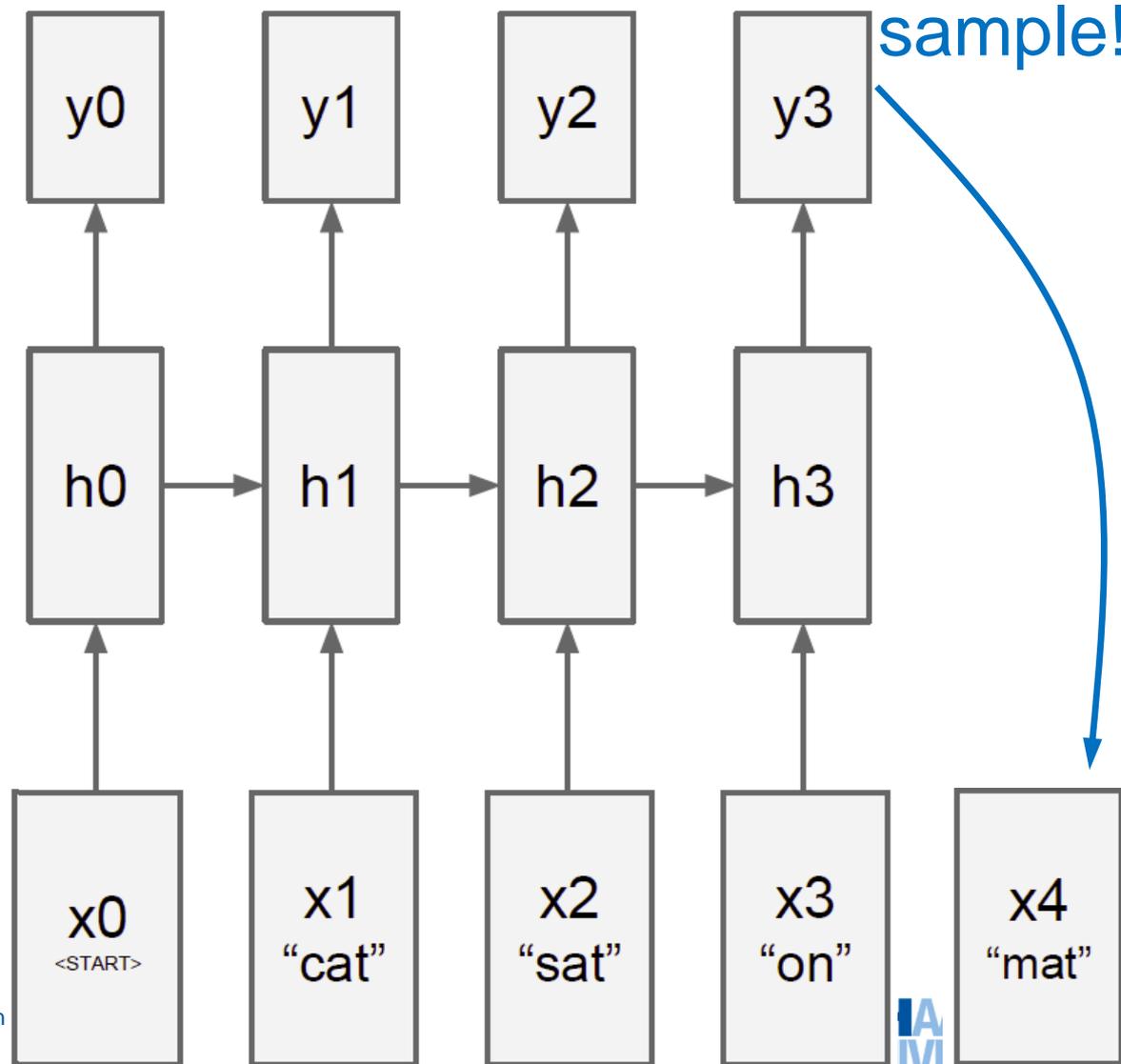
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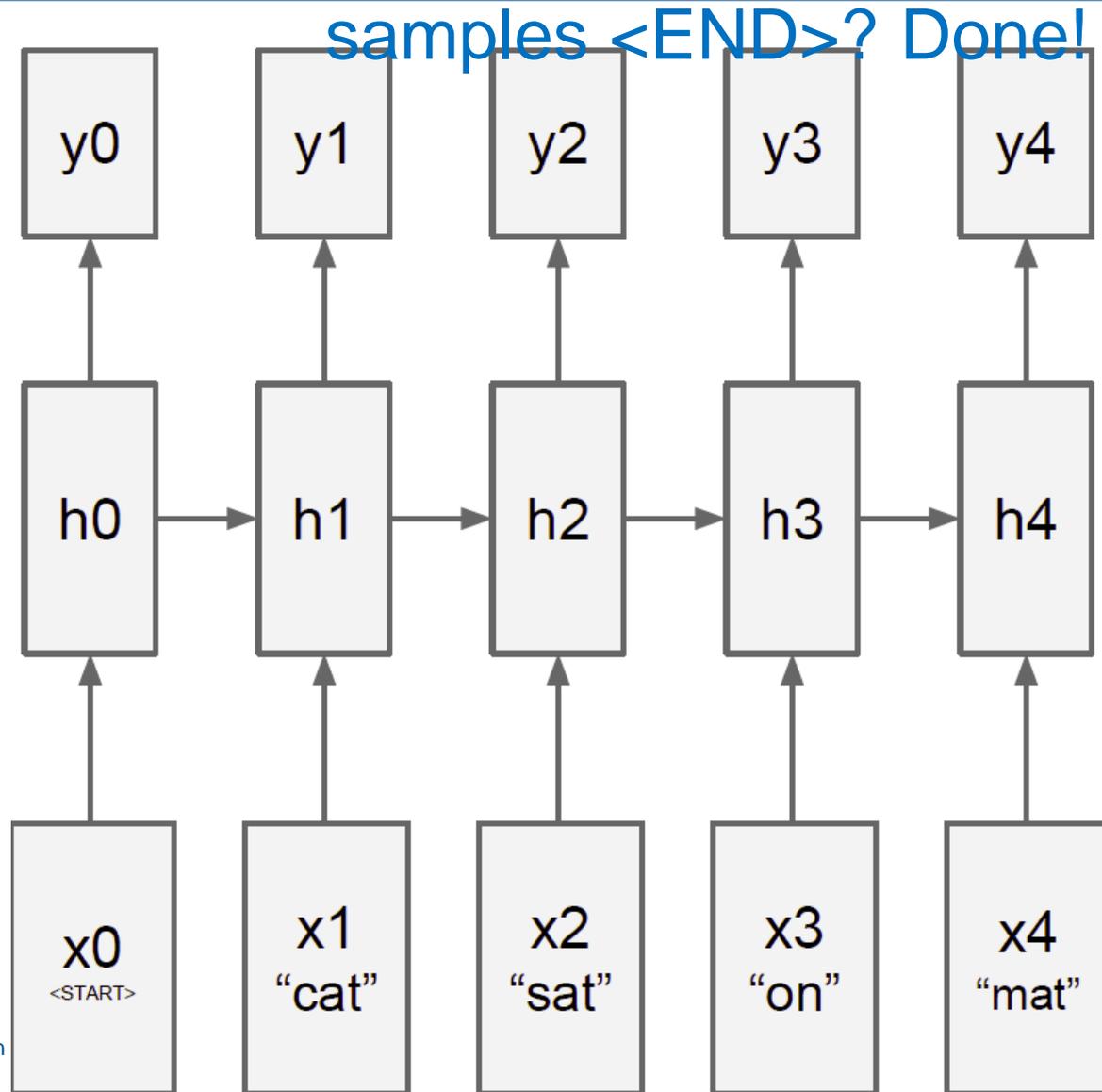
$$p(\textit{next word} \mid \textit{previous words})$$



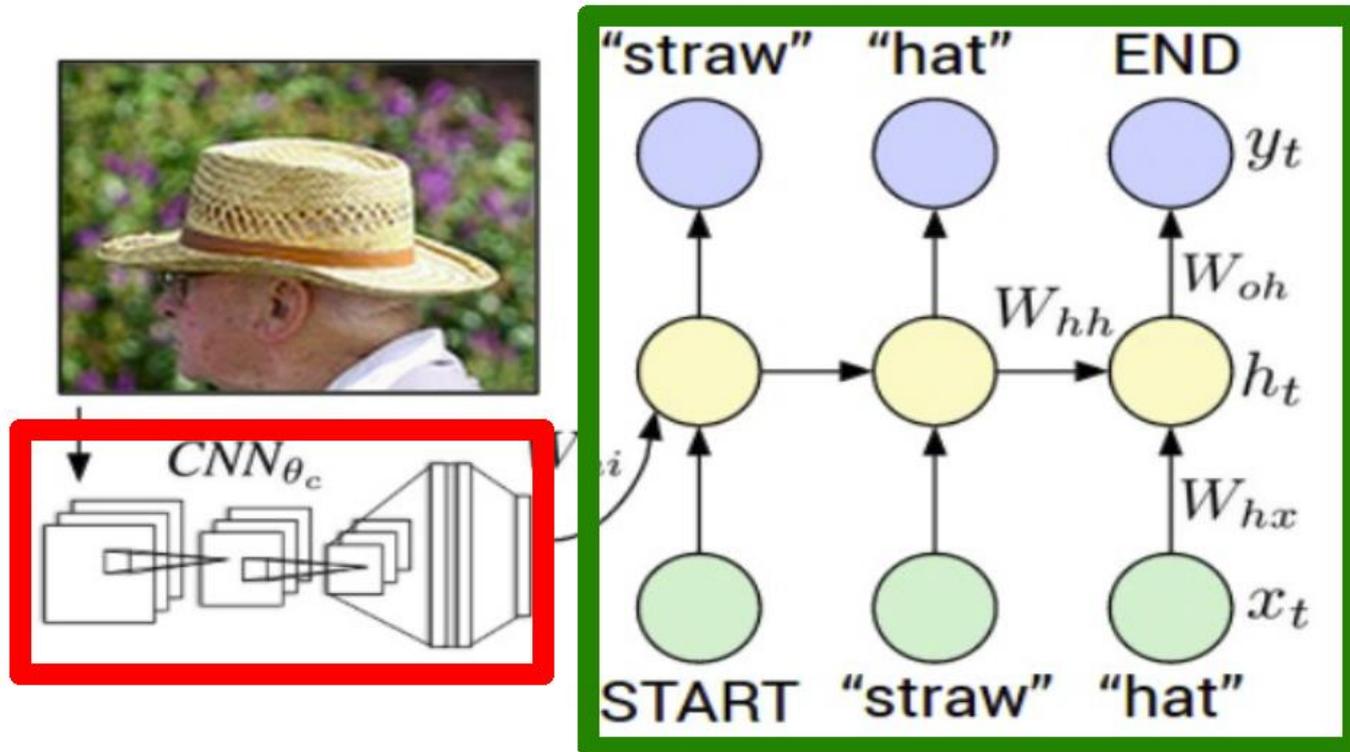
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$$p(\text{next word} \mid \text{previous words})$$



# Applications: Image Tagging



- Simple combination of CNN and RNN
  - Use CNN to define initial state  $h_0$  of an RNN.
  - Use RNN to produce text description of the image.

# Applications: Image Tagging

- Setup

- Train on corpus of images with textual descriptions
- E.g. Microsoft CoCo
  - 120k images
  - 5 sentences each

a man riding a bike on a dirt path through a forest.  
bicyclist raises his fist as he rides on desert dirt trail.  
this dirt bike rider is smiling and raising his fist in triumph.  
a man riding a bicycle while pumping his fist in the air.  
a mountain biker pumps his fist in celebration.



# Results: Image Tagging



a group of people standing around a room with remotes  
logprob: -9.17



a young boy is holding a baseball bat  
logprob: -7.61



a cow is standing in the middle of a street  
logprob: -8.84

*Spectacular results!*

# Results: Image Tagging



a baby laying on a bed with a stuffed bear  
logprob: -8.66



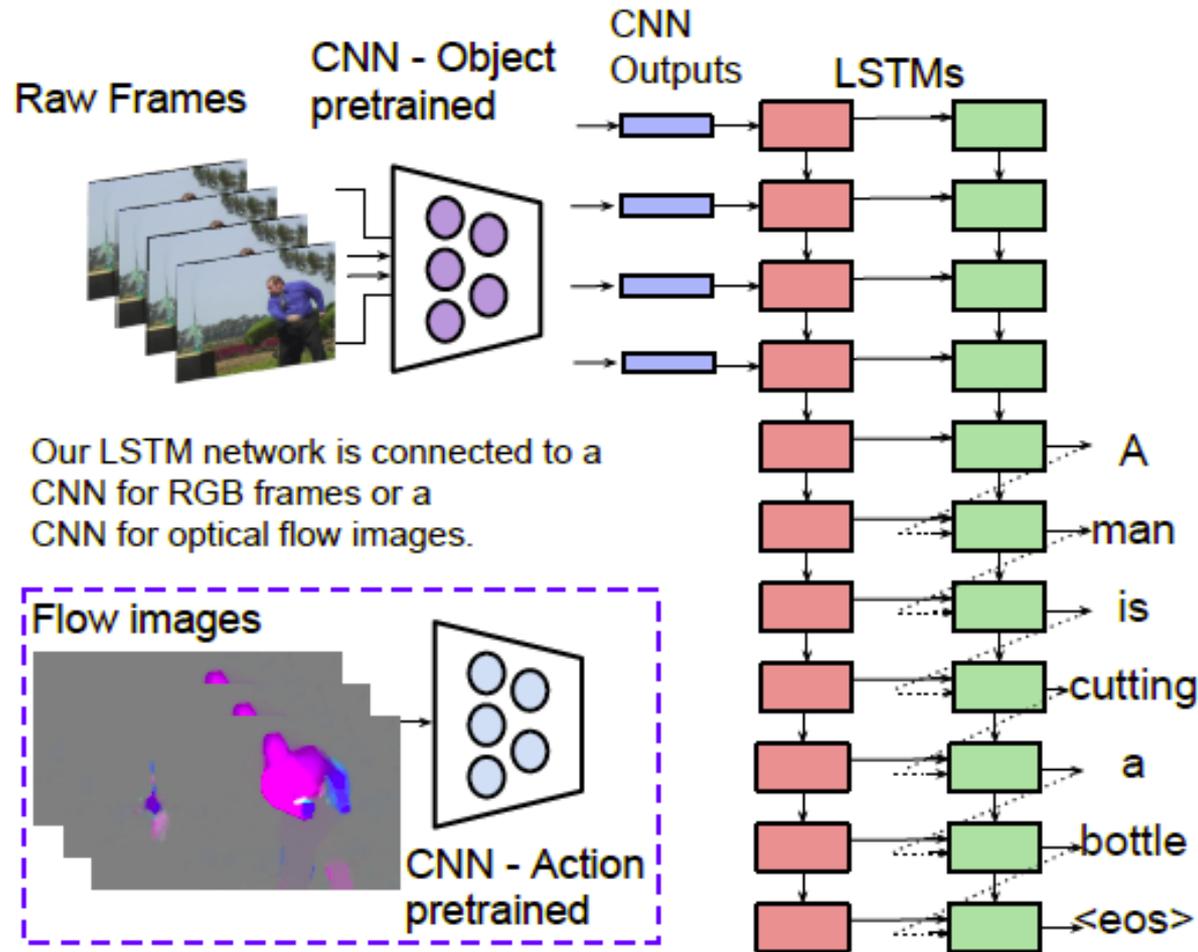
a young boy is holding a  
baseball bat  
logprob: -7.65



a cat is sitting on a couch with a remote control  
logprob: -12.45

- Wrong, but one can still see why those results were selected...

# Application: Video to Text Description

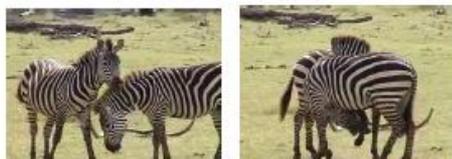


# Video-to-Text Results

## Correct descriptions.



S2VT: A man is doing stunts on his bike.



ZVT: A herd of zebras are walking in a field.



S2VT: A young woman is doing her hair.

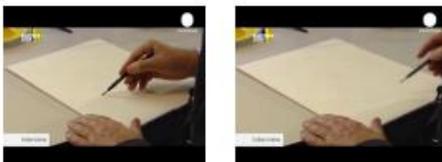


S2VT: A man is shooting a gun at a target.

## Relevant but incorrect descriptions.



S2VT: A small bus is running into a building.



S2VT: A man is cutting a piece of a pair of a paper.



S2VT: A cat is trying to get a small board.



S2VT: A man is spreading butter on a tortilla.

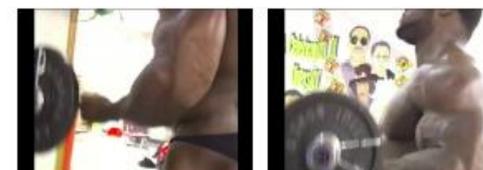
## Irrelevant descriptions.



S2VT: A man is pouring liquid in a pan.



S2VT: A polar bear is walking on a hill.



S2VT: A man is doing a pencil.



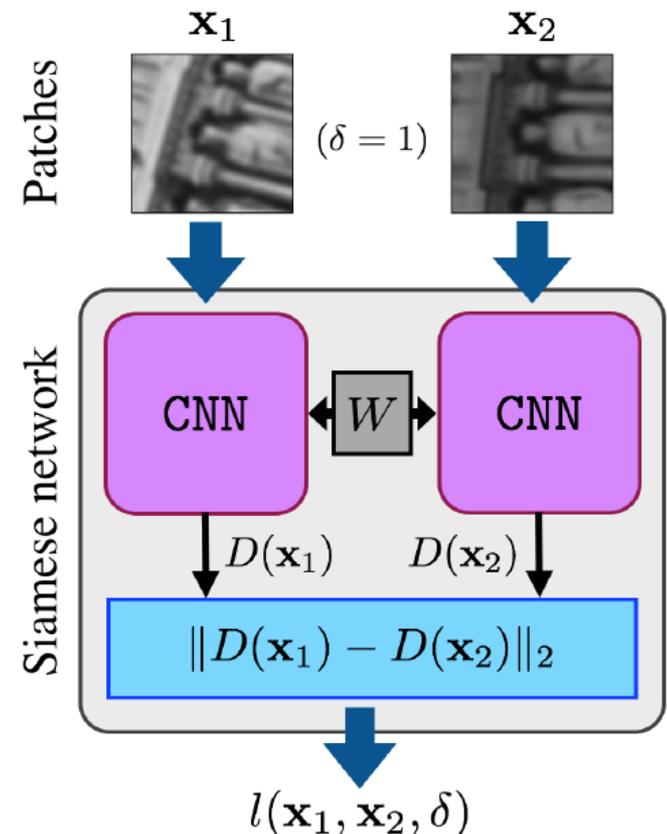
S2VT: A black clip to walking through a path.

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# Learning Similarity Functions

- Siamese Network
  - Present the two stimuli to two identical copies of a network (with shared parameters)
  - Train them to output similar values if the inputs are (semantically) similar.
- Used for many matching tasks
  - Face identification
  - Stereo estimation
  - Optical flow
  - ...

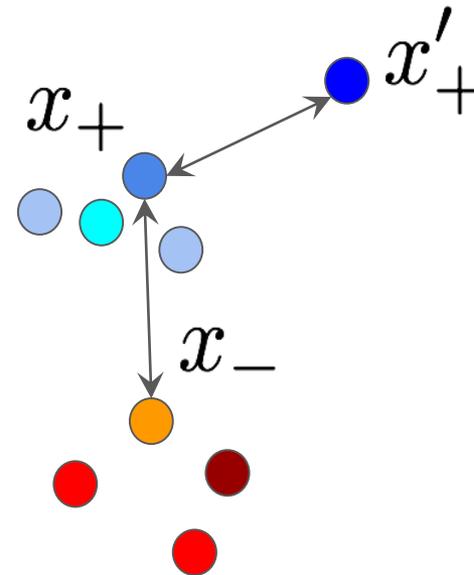


# Metric Learning: Contrastive Loss

- Mapping an image to a metric embedding space
  - Metric space: distance relationship = class membership

$$\|f(x) - f(x_+)\| \rightarrow 0$$

$$\|f(x) - f(x_-)\| \geq m$$

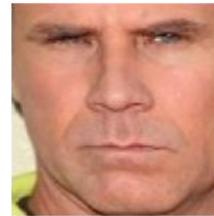


Yi et al., LIFT: Learned Invariant Feature Transform, ECCV 16

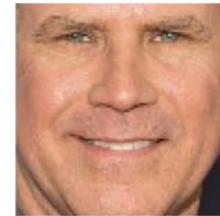
# Metric Learning: Triplet Loss

- Learning a discriminative embedding
  - Present the network with triplets of examples

Negative

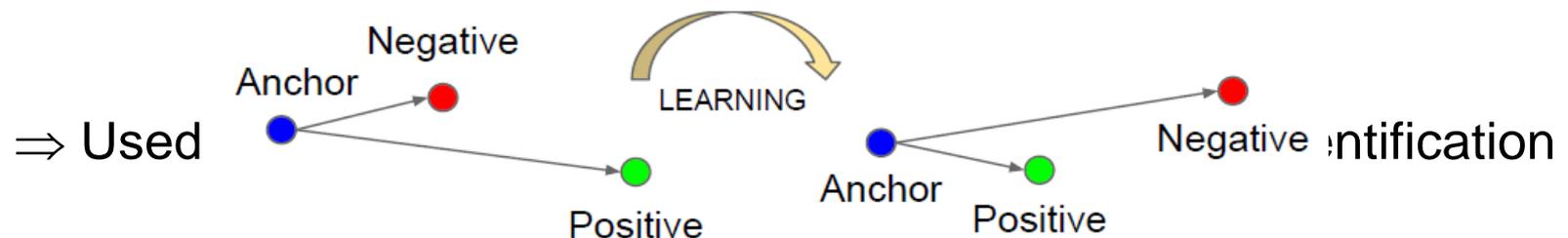


Positive



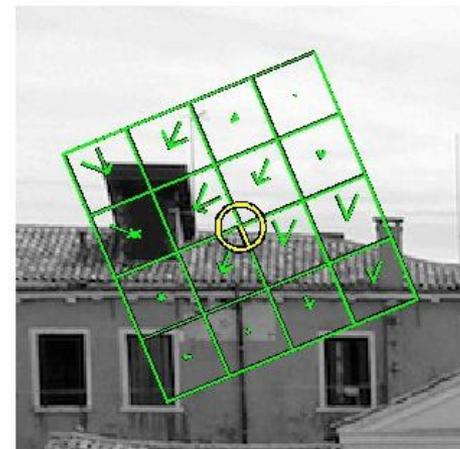
- Apply triplet loss to learn an embedding  $f(\cdot)$  that groups the positive example closer to the anchor than the negative one.

$$\|f(x_i^a) - f(x_i^p)\|_2^2 < \|f(x_i^a) - f(x_i^n)\|_2^2$$



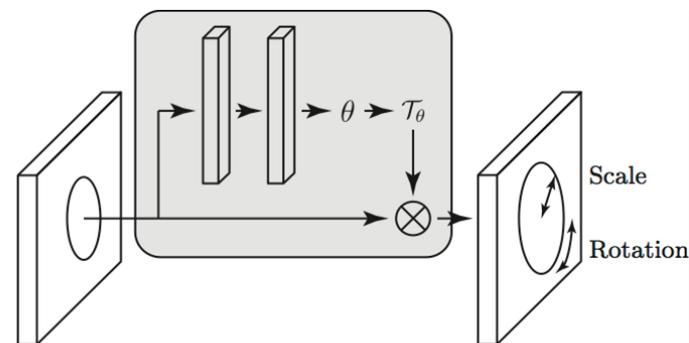
# Patch Normalization with Spatial Transformer Nets

- Patch Normalization
  - Key component of local feature matching
  - Finding the scale and rotation
  - Invariant to perspective transformation



[SIFT patch normalization]

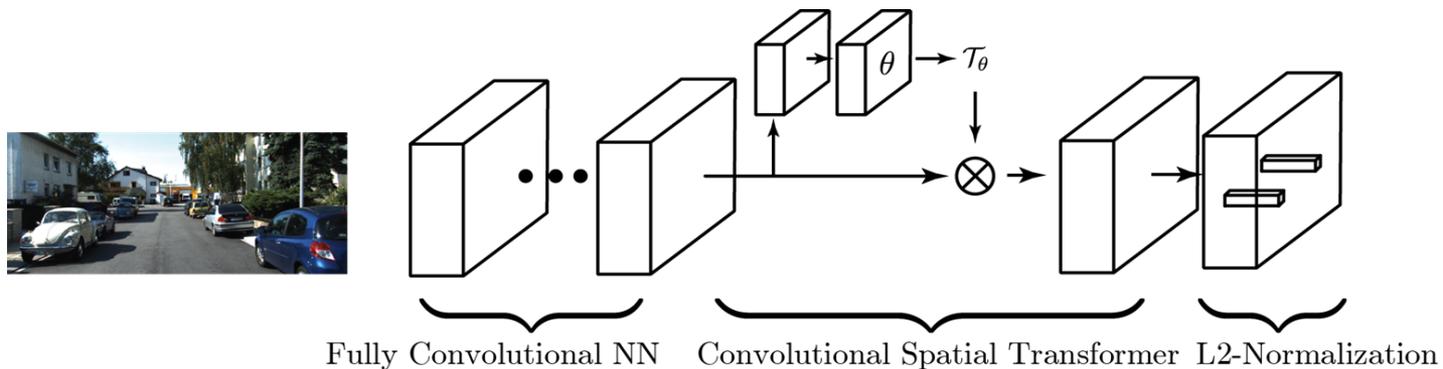
- Spatial Transformer Network
  - Adaptively apply transformation



[Spatial Transformer Network]

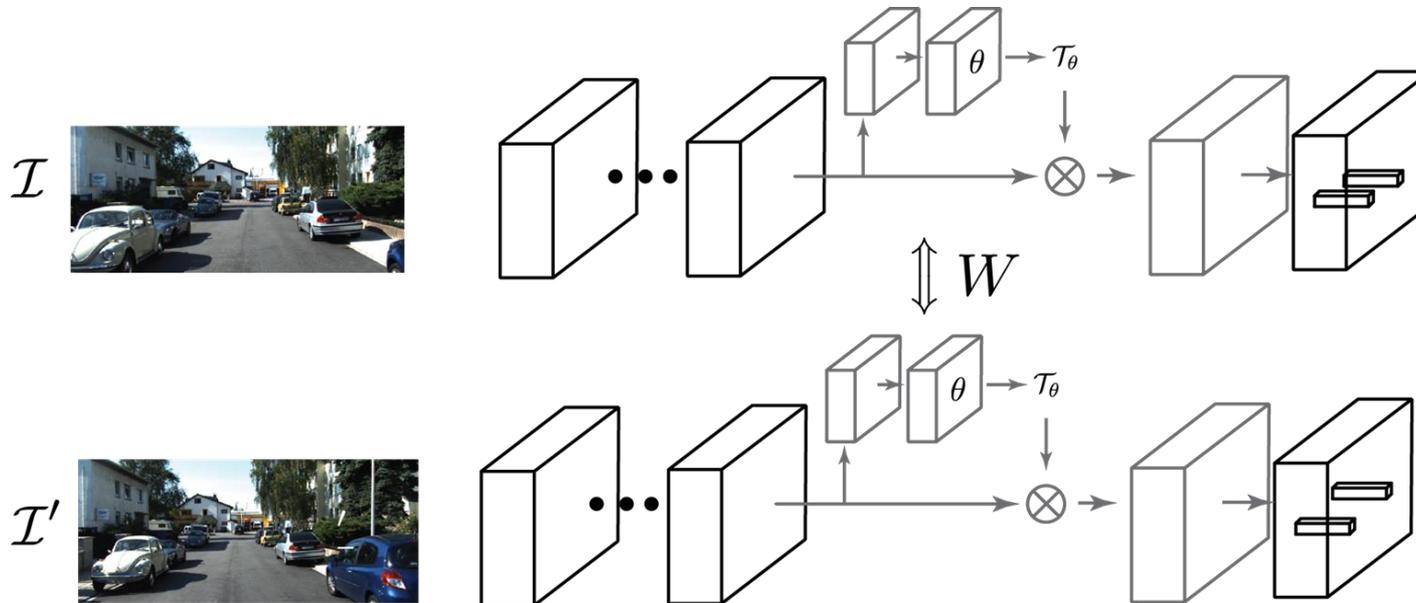
# Universal Correspondence Network

- Computing a patch descriptor



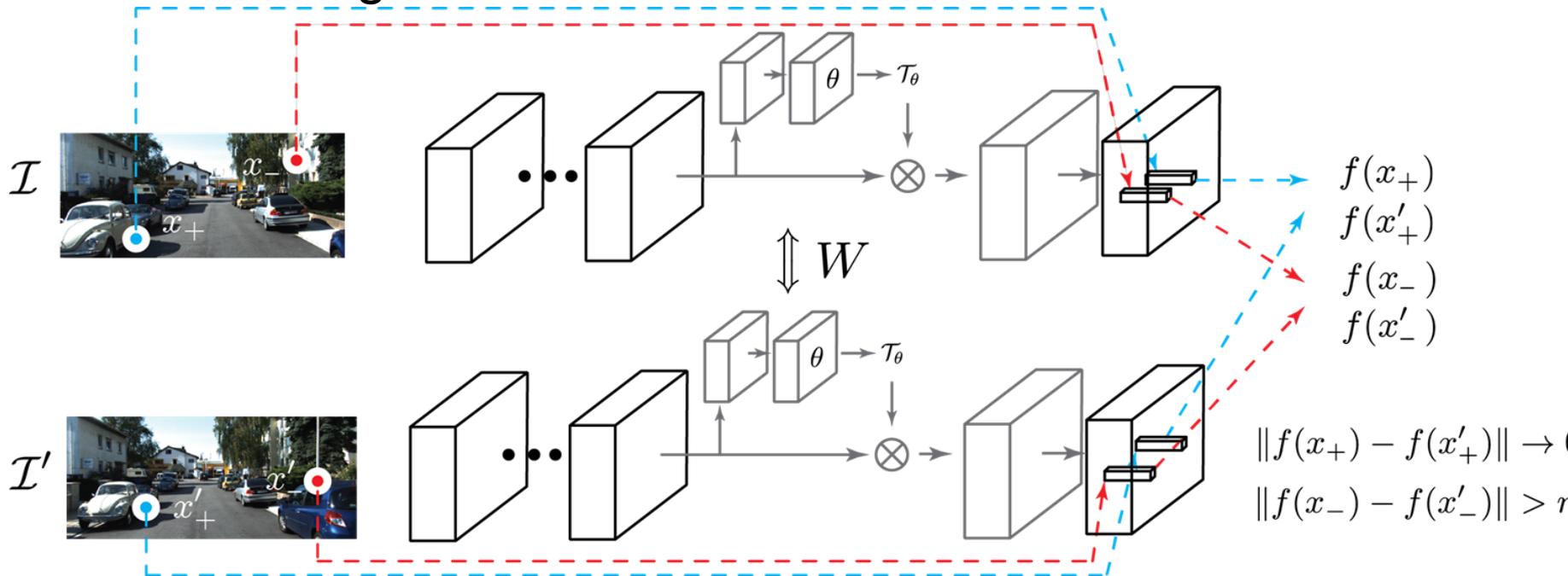
# Universal Correspondence Network

- Siamese architecture for matching patches



# Universal Correspondence Network

- UCN Training

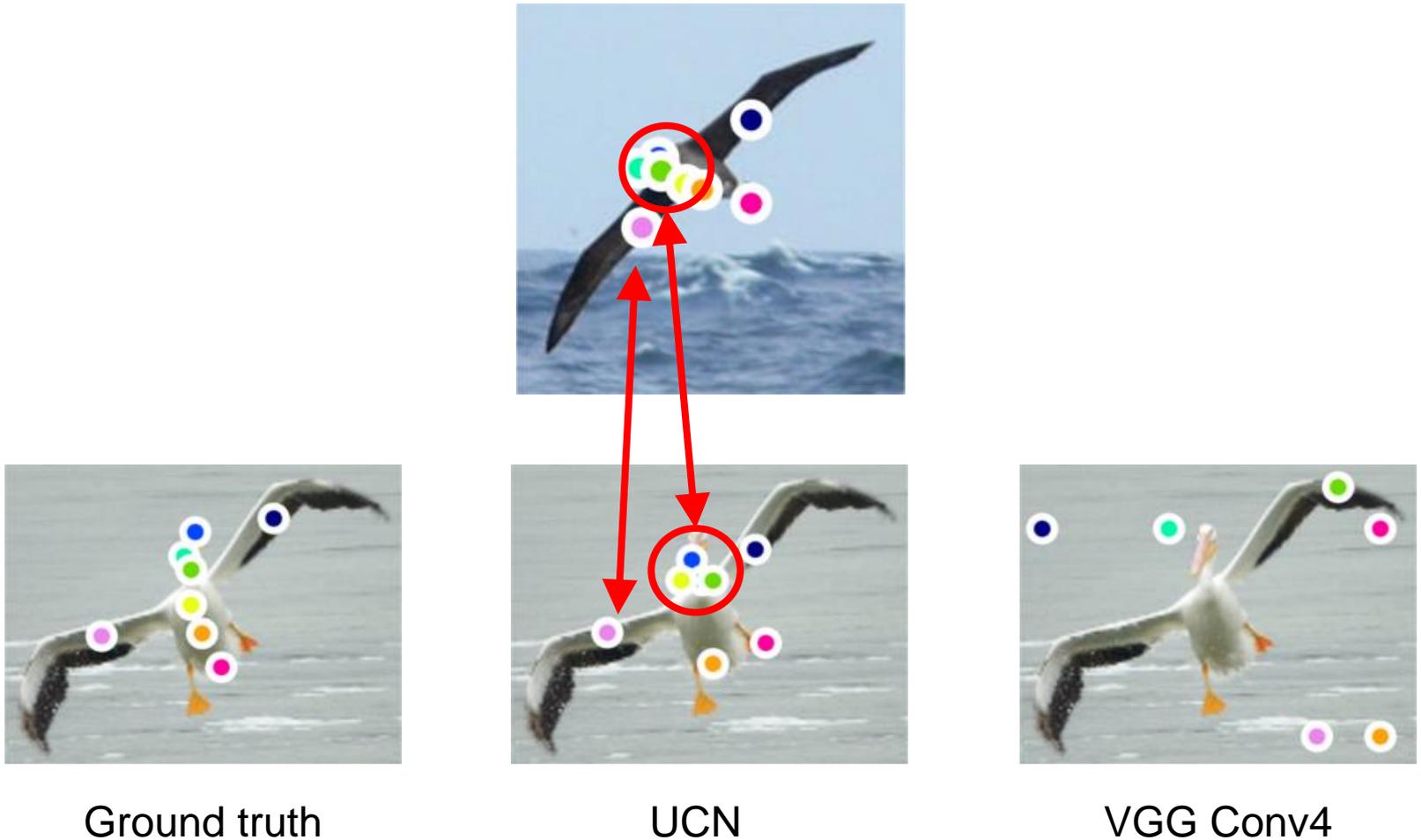


- Contrastive loss

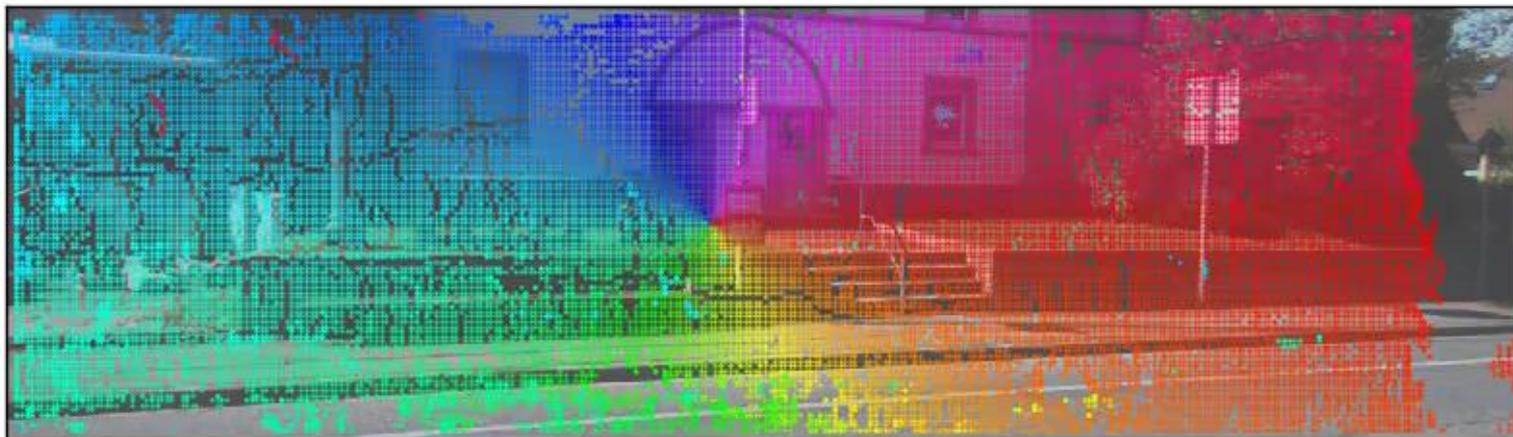
$$\|f(x_+) - f(x'_+)\| \rightarrow 0$$

$$\|f(x_-) - f(x'_-)\| > m$$

# Semantic Correspondences with UCN



# Exact Correspondences with UCN (Disparity Estimation)



C. Choy, J.Y. Gwak, S. Savarese, M. Chandraker, [Universal Correspondence Network](#), NIPS'16

# References and Further Reading

- RNNs

- R. Pascanu, T. Mikolov, Y. Bengio, [On the difficulty of training recurrent neural networks](#), JMLR, Vol. 28, 2013.
- A. Karpathy, [The Unreasonable Effectiveness of Recurrent Neural Networks](#), blog post, May 2015.

- LSTM

- S. Hochreiter , J. Schmidhuber, [Long short-term memory](#), Neural Computation, Vol. 9(8): 1735–1780, 1997.
- A. Graves, [Generating Sequences With Recurrent Neural Networks](#), ArXiv 1308.0850v5, 2014.
- C. Olah, [Understanding LSTM Networks](#), blog post, August 2015.