Advanced Machine Learning
Lecture 1

Introduction

20.10.2015

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Language

• Official course language will be English
  - If at least one English-speaking student is present.
  - If not... you can choose.

  However...
  - Please tell me when I’m talking too fast or when I should repeat
    something in German for better understanding!
  - You may at any time ask questions in German!
  - You may turn in your exercises in German.
  - You may take the oral exam in German.

Relationship to Previous Courses

• Lecture Machine Learning (past summer semester)
  - Introduction to ML
  - Classification
  - Graphical models

• This course: Advanced Machine Learning
  - Natural continuation of ML course
  - Deeper look at the underlying concepts
  - But: will try to make it accessible also to newcomers
  - Quick poll: Who hasn’t heard the ML lecture?

• This year: Lots of new material
  - Large lecture block on Deep Learning
  - First time for us to teach this (so, bear with us...)

New Content This Year

Deep Learning

Organization

• Lecturer
  - Prof. Bastian Leibe (leibe@vision.rwth-aachen.de)

• Teaching Assistants
  - Umer Rafi (rafi@vision.rwth-aachen.de)
  - Lucas Beyer (beyer@vision.rwth-aachen.de)

• Course webpage
  - http://www.vision.rwth-aachen.de/teaching/
  - Slides will be made available on the webpage
  - There is also an L2P electronic repository

• Please subscribe to the lecture on the Campus system!
  - Important to get email announcements and L2P access!
Course Webpage

Tentative Schedule

<table>
<thead>
<tr>
<th>Date</th>
<th>Topic</th>
<th>Content</th>
<th>Slides</th>
<th>Related Material</th>
</tr>
</thead>
<tbody>
<tr>
<td>19.10.15</td>
<td>Introduction, Polynomial Fitting, Least-Squares Regression, Decision Trees, Regression, Ridge</td>
<td>phone_ch.1, 2, 3, 4, 5</td>
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<td></td>
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</tbody>
</table>

Monday: Matlab tutorial

Exercises and Supplementary Material

- **Exercises**
  - Typically 1 exercise sheet every 2 weeks.
  - Pen & paper and programming exercises
    - Matlab for early topics
    - Theano for Deep Learning topics
  - Hands-on experience with the algorithms from the lecture.
  - Send your solutions the night before the exercise class.

- **Supplementary material**
  - Research papers and book chapters
  - Will be provided on the webpage.

Textbooks

- Most lecture topics will be covered in Bishop’s book.
- Some additional topics can be found in Rasmussen & Williams.

Christopher M. Bishop
Pattern Recognition and Machine Learning
Springer, 2006

Carl E. Rasmussen, Christopher K.I. Williams
Gaussian Processes for Machine Learning
MIT Press, 2006
(also available online: http://www.gaussianprocess.org/gpml/)

- Research papers will be given out for some topics.
  - Tutorials and deeper introductions.
  - Application papers

How to Find Us

- **Office:**
  - UMIC Research Centre
  - Mies-van-der-Rohe-Strasse 15, room 124

- **Office hours**
  - If you have questions to the lecture, come see us.
  - My regular office hours will be announced.
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Questions are welcome!

Machine Learning

- **Statistical Machine Learning**
  - Principles, methods, and algorithms for learning and prediction on the basis of past evidence

- Already everywhere
  - Speech recognition (e.g. speed-dialing)
  - Computer vision (e.g. face detection)
  - Hand-written character recognition (e.g. letter delivery)
  - Information retrieval (e.g. image & video indexing)
  - Operation systems (e.g. caching)
  - Fraud detection (e.g. credit cards)
  - Text filtering (e.g. email spam filters)
  - Game playing (e.g. strategy prediction)
  - Robotics (e.g. prediction of battery lifetime)

What Is Machine Learning Useful For?

Automatic Speech Recognition

Siri, your wish is its command.

Automatic Speech Recognition

Slide adapted from Zeeshan Gharamani

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What Is Machine Learning Useful For?

Computer Vision
(Object Recognition, Segmentation, Scene Understanding)

Information Retrieval
(Retrieval, Categorization, Clustering, ...)

Financial Prediction
(Time series analysis, ...)

Medical Diagnosis
(Inference from partial observations)

Bioinformatics
(Modeling gene microarray data, ...)

Robotics
(DARPA Grand Challenge, ...)

Image from Kevin Murphy
Machine Learning: Core Questions

- Learning to perform a task from experience
  - Task
    - Can often be expressed through a mathematical function
      \[ y = f(x; w) \]
    - \( x \): Input
    - \( y \): Output
    - \( w \): Parameters (this is what is "learned")

- Classification vs. Regression
  - Regression: continuous \( y \)
  - Classification: discrete \( y \)
    - E.g. class membership, sometimes also posterior probability

\[ y = f(x; w) \]

A Look Back: Lecture Machine Learning

- Fundamentals
  - Bayes Decision Theory
  - Probability Density Estimation

- Classification Approaches
  - Linear Discriminant Functions
  - Support Vector Machines
  - Ensemble Methods & Boosting
  - Randomized Trees, Forests & Ferns

- Generative Models
  - Bayesian Networks
  - Markov Random Fields

This Lecture: Advanced Machine Learning

Extending lecture Machine Learning from last semester...

- Regression Approaches
  - Linear Regression
  - Regularization (Ridge, Lasso)
  - Gaussian Processes

- Learning with Latent Variables
  - EM and Generalizations
  - Approximate Inference

- Deep Learning
  - Neural Networks
  - CNNs, RNNs, RBMs, etc.

Let's Get Started...

- Some of you already have basic ML background
  - Who hasn't?

- We’ll start with a gentle introduction
  - I’ll try to make the lecture also accessible to newcomers
  - We’ll review the main concepts before applying them
  - I’ll point out chapters to review from ML lecture whenever knowledge from there is needed/helpful
  - But please tell me when I’m moving too fast (or too slow)

Topics of This Lecture

- Regression: Motivation
  - Polynomial fitting
  - General Least-Squares Regression
  - Overfitting problem
  - Regularization
  - Ridge Regression

- Recap: Important Concepts from ML Lecture
  - Probability Theory
  - Bayes Decision Theory
  - Maximum Likelihood Estimation
  - Bayesian Estimation

- A Probabilistic View on Regression
  - Least-Squares Estimation as Maximum Likelihood
Regression

- Learning to predict a continuous function value
  - Given: training set \( X = \{ x_1, \ldots, x_N \} \) with target values \( T = \{ t_1, \ldots, t_N \} \).
  - \( \Rightarrow \) Learn a continuous function \( y(x) \) to predict the function value for a new input \( x \).
- Steps towards a solution
  - Choose a form of the function \( y(x, w) \) with parameters \( w \).
  - Define an error function \( E(w) \) to optimize.
  - Optimize \( E(w) \) for \( w \) to find a good solution.
  - Derive the properties of this solution and think about its limitations.

Example: Polynomial Curve Fitting

- Toy dataset
  - Generated by function \( f(x) = \sin(2\pi x) + \epsilon \)
  - Small level of random noise with Gaussian distribution added (blue dots)
- Goal: fit a polynomial function to this data
  - \( y(x, w) = w_0 + w_1 x + w_2 x^2 + \ldots + w_M x^M \)
  - Note: Nonlinear function of \( x \), but linear function of the \( w_j \).

Error Function

- How to determine the values of the coefficients \( w \)?
  - We need to define an error function to be minimized.
  - This function specifies how a deviation from the target value should be weighted.
- Popular choice: sum-of-squares error
  - Definition
    \[
    E(w) = \frac{1}{2} \sum_{n=1}^{N} (y(x_n, w) - t_n)^2
    \]
  - We’ll discuss the motivation for this particular function later...

Minimizing the Error

- How do we minimize the error?
  - \( E(w) = \frac{1}{2} \sum_{n=1}^{N} (y(x_n, w) - t_n)^2 \)
- Solution (Always!)
  - Compute the derivative and set it to zero.
    \[
    \frac{\partial E(w)}{\partial w_j} = \sum_{n=1}^{N} (y(x_n, w) - t_n) \frac{\partial y(x_n, w)}{\partial w_j} = 0
    \]
  - Since the error is a quadratic function of \( w \), its derivative will be linear in \( w \).
  - \( \Rightarrow \) Minimization has a unique solution.

Least-Squares Regression

- We have given
  - Training data points: \( X = \{ x_1 \in \mathbb{R}^d, \ldots, x_n \} \)
  - Associated function values: \( T = \{ t_1 \in \mathbb{R}, \ldots, t_n \} \)
- \( \Rightarrow \) Learn a linear function to predict the function value for a new input \( x \).
- Start with linear regressor:
  - Try to enforce \( x_i^T \hat{w} + w_0 = t_i, \quad \forall i = 1, \ldots, n \)
  - One linear equation for each training data point / label pair.
  - This is the same basic setup used for least-squares classification!
    - Only the values are now continuous.

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- Setup
  - Step 1: Define \( \tilde{x}_i = \begin{pmatrix} x_i \\ 1 \end{pmatrix} \), \( \tilde{w} = \begin{pmatrix} w \\ w_0 \end{pmatrix} \)
  - Step 2: Rewrite \( \tilde{x}_i^T \tilde{w} = t_i, \quad \forall i = 1, \ldots, n \)
  - Step 3: Matrix-vector notation
    \[
    X \tilde{w} = t \quad \text{with} \quad X = [\tilde{x}_1, \ldots, \tilde{x}_n], \quad t = [t_1, \ldots, t_n]^T
    \]
  - Step 4: Find least-squares solution
    \[
    |X \tilde{w} - t|^2 \rightarrow \min
    \]
  - Solution: \( \hat{w} = (XX^T)^{-1} X t \)
Regression with Polynomials

- How can we fit arbitrary polynomials using least-squares regression?
  - We introduce a feature transformation (as before in ML).
    \[ y(x) = w^T \phi(x) \]
    \[ = \sum_{i=0}^{M} w_i \phi_i(x) \]
  - E.g.: \( \phi(x) = (1, x, x^2, x^3)^T \)
  - Fitting a cubic polynomial.

Varying the Order of the Polynomial.

- Which one should we pick?

Analysis of the Results

- Results for different values of \( M \)
  - Best representation of the original function \( \sin(2\pi x) \) with \( M = 3 \).
  - Perfect fit to the training data with \( M = 9 \), but poor representation of the original function.
- Why is that???
  - After all, \( M = 9 \) contains \( M = 3 \) as a special case!

Overfitting

- Problem
  - Training data contains some noise
    \[ f(x) = \sin(2\pi x) + \epsilon \]
  - Higher-order polynomial fitted perfectly to the noise.
  - We say it was overfitting to the training data.
- Goal is a good prediction of future data
  - Our target function should fit well to the training data, but also generalize.
  - Measure generalization performance on independent test set.

Measuring Generalization

- E.g., Root Mean Square Error (RMS): \( E_{\text{RMS}} = \sqrt{2E(w^*)/N} \)
- Motivation
  - Division by \( N \) lets us compare different data set sizes.
  - Square root ensures \( E_{\text{RMS}} \) is measured on the same scale (and in the same units) as the target variable \( t \).

Analyzing Overfitting

- Example: Polynomial of degree 9

\( \Rightarrow \) Overfitting becomes less of a problem with more data.
What Is Happening Here?

- The coefficients get very large:
  - Fitting the data from before with various polynomials.
  - Coefficients:

<table>
<thead>
<tr>
<th>M = 0</th>
<th>M = 1</th>
<th>M = 3</th>
<th>M = 9</th>
</tr>
</thead>
<tbody>
<tr>
<td>( w_0 )</td>
<td>0.35</td>
<td>0.35</td>
<td>0.33</td>
</tr>
<tr>
<td>( w_1 )</td>
<td>232.37</td>
<td>4.74</td>
<td>-0.05</td>
</tr>
<tr>
<td>( w_2 )</td>
<td>-4629.43</td>
<td>-0.77</td>
<td>-0.06</td>
</tr>
<tr>
<td>( w_3 )</td>
<td>48568.31</td>
<td>-31.97</td>
<td>-0.06</td>
</tr>
<tr>
<td>( w_4 )</td>
<td>-231639.30</td>
<td>-3.89</td>
<td>-0.60</td>
</tr>
<tr>
<td>( w_5 )</td>
<td>-896432.26</td>
<td>55.28</td>
<td>-0.02</td>
</tr>
<tr>
<td>( w_6 )</td>
<td>-1061900.52</td>
<td>41.32</td>
<td>-0.01</td>
</tr>
<tr>
<td>( w_7 )</td>
<td>10498001.16</td>
<td>-45.95</td>
<td>-0.00</td>
</tr>
<tr>
<td>( w_8 )</td>
<td>-5557825.99</td>
<td>-91.53</td>
<td>0.00</td>
</tr>
<tr>
<td>( w_9 )</td>
<td>125361.43</td>
<td>72.66</td>
<td>0.03</td>
</tr>
</tbody>
</table>

Regularization

- What can we do then?
  - How can we apply the approach to data sets of limited size?
  - We still want to use relatively complex and flexible models.
- Workaround: Regularization
  - Penalize large coefficient values
    \[
    \hat{E}(w) = \frac{1}{2} \sum_{i=1}^{N} (y(x_i, w) - t_n)^2 + \frac{\lambda}{2} \|w\|^2
    \]
  - Here we’ve simply added a quadratic regularizer, which is simple to optimize
  - The resulting form of the problem is called Ridge Regression.
  - \( \lambda \) is often omitted from the regularizer.

Results with Regularization (M=9)

- Effect of regularization
  - The trade-off parameter \( \lambda \) now controls the effective model complexity and thus the degree of overfitting.

Summary

- We’ve seen several important concepts
  - Linear regression
  - Overfitting
  - Role of the amount of data
  - Role of model complexity
  - Regularization
- How can we approach this more systematically?
  - Would like to work with complex models.
  - How can we prevent overfitting systematically?
  - How can we avoid the need for validation on separate test data?
  - What does it mean to do linear regression?
  - What does it mean to do regularization?

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Recap: The Rules of Probability

- Basic rules
  
  \[ p(X) = \sum_{Y} p(X, Y) \]

  \[ p(X, Y) = p(Y|X)p(X) \]

- From those, we can derive
  
  \[ p(Y|X) = \frac{p(X|Y)p(Y)}{p(X)} \]

  where

  \[ p(X) = \sum_{Y} p(X|Y)p(Y) \]

Recap: Gaussian (or Normal) Distribution

- One-dimensional case
  
  \[ N(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{ -\frac{(x - \mu)^2}{2\sigma^2} \right\} \]

- Multi-dimensional case
  
  \[ N(x; \mu, \Sigma) = \frac{1}{(2\pi)^{D/2}|\Sigma|^{1/2}} \exp\left\{ -\frac{1}{2}(x - \mu)^T\Sigma^{-1}(x - \mu) \right\} \]

Recap: Parametric Methods

- Given
  
  - Data \( X = \{x_1, x_2, \ldots, x_N\} \)
  - Parametric form of the distribution with parameters \( \theta \)
  - E.g. for Gaussian distribution: \( \theta = (\mu, \sigma) \)

- Learning
  
  - Estimation of the parameters \( \theta \)

- Likelihood of \( \theta \)
  
  - Probability that the data \( X \) have indeed been generated from a probability density with parameters \( \theta \)
  
  \[ L(\theta) = p(X|\theta) \]

Recap: Bayes Decision Theory

- Notation
  
  In many situations, it will be necessary to work with the inverse of the covariance matrix \( \Sigma \):

  \[ \Delta = \Sigma^{-1} \]

  - We call \( \Delta \) the precision matrix.

  - We can also write the Gaussian as

  \[ N(x; \mu, \Lambda^{-1}) = \frac{1}{\sqrt{(2\pi)^D|\Lambda|^{1/2}}} \exp\left\{ -\frac{1}{2}(x - \mu)^T\Lambda^{-1}(x - \mu) \right\} \]

Recap: Maximum Likelihood Approach

- Computation of the likelihood
  
  - Single data point: \( p(x_n|\theta) \)

  - Assumption: all data points \( X = \{x_1, \ldots, x_n\} \) are independent

  \[ L(\theta) = p(X|\theta) = \prod_{n=1}^{N} p(x_n|\theta) \]

  - Log-likelihood

  \[ E(\theta) = -\ln L(\theta) = -\sum_{n=1}^{N} \ln p(x_n|\theta) \]

- Estimation of the parameters \( \theta \) (Learning)
  
  - Maximize the likelihood (or minimize the negative log-likelihood)

  \[ \frac{d}{d\theta} E(\theta) = -\sum_{n=1}^{N} \frac{\partial p(x_n|\theta)}{p(x_n|\theta)} \frac{d\theta}{d\theta} = 0 \]
Recap: Maximum Likelihood - Limitations

- Maximum Likelihood has several significant limitations
  - It systematically underestimates the variance of the distribution!
  - E.g. consider the case
    \[ N = 1, X = \{ x_1 \} \]
    \[ \Rightarrow \text{Maximum-likelihood estimate:} \]
    \[ \hat{x} = 0 ! \]
  - We say ML overfits to the observed data.
  - We will still often use ML, but it is important to know about this effect.

Recap: Deeper Reason

- Maximum Likelihood is a Frequentist concept
  - In the Frequentist view, probabilities are the frequencies of random, repeatable events.
  - These frequencies are fixed, but can be estimated more precisely when more data is available.

- This is in contrast to the Bayesian interpretation
  - In the Bayesian view, probabilities quantify the uncertainty about certain states or events.
  - This uncertainty can be revised in the light of new evidence.

- Bayesians and Frequentists do not like each other too well...

Recap: Bayesian Learning Approach

- Bayesian view:
  - Consider the parameter vector \( \theta \) as a random variable.
  - When estimating the parameters, what we compute is
    \[ p(x|X) = \int p(x, \theta|X) d\theta \]
    \[ p(x, \theta|X) = p(x|\theta, X)p(\theta|X) \]
    \[ p(x|X) = \int p(x|\theta)p(\theta|X) d\theta \]
  - This is entirely determined by the parameter \( \theta \)
    (i.e. by the parametric form of the pdf).

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References and Further Reading

- More information, including a short review of Probability theory and a good introduction in Bayes Decision Theory can be found in Chapters 1.1, 1.2 and 1.5 of

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