

Advanced Machine Learning Lecture 6

Probability Distributions

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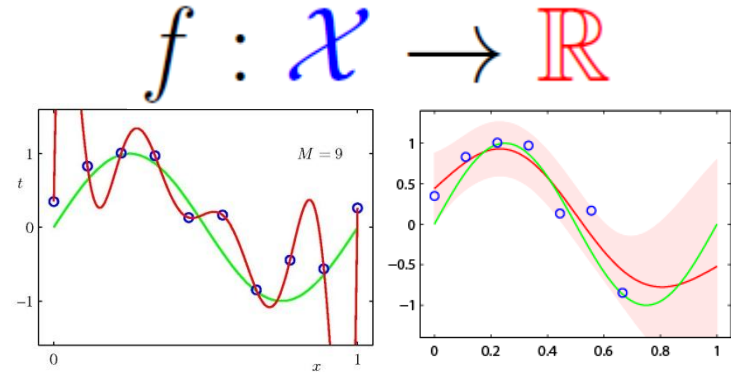
Announcement

- Exercise sheet 1 online
 - Linear Regression
 - Ridge Regression
 - Kernel Ridge Regression
 - Gaussian Process Regression
 - Exercise will be on Monday, 19.11.
⇒ *Please submit your results until 18.11. midnight.*

This Lecture: *Advanced Machine Learning*

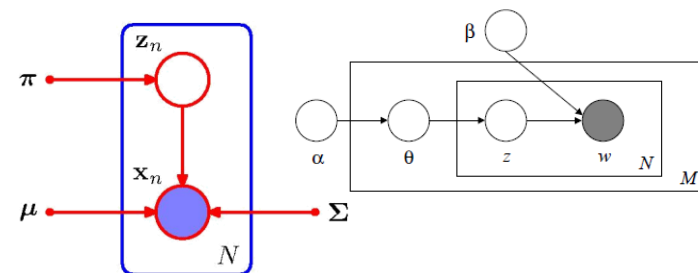
• Regression Approaches

- Linear Regression
- Regularization (Ridge, Lasso)
- Kernels (Kernel Ridge Regression)
- Gaussian Processes



• Bayesian Estimation & Bayesian Non-Parametrics

- **Mixture Models & EM**
- Dirichlet Processes
- Latent Factor Models
- Beta Processes



• SVMs and Structured Output Learning

- SV Regression, SVDD
- Large-margin Learning

$$f : \mathcal{X} \rightarrow \mathcal{Y}$$

Recap: Bayesian Model Selection for GPs

- **Goal**
 - Determine/learn different parameters of Gaussian Processes
- **Hierarchy of parameters**
 - **Lowest level**
 - w - e.g. parameters of a linear model.
 - **Mid-level (hyperparameters)**
 - θ - e.g. controlling prior distribution of w .
 - **Top level**
 - Typically discrete set of model structures \mathcal{H}_i .
- **Approach**
 - Inference takes place one level at a time.

Recap: Model Selection at Lowest Level

- Posterior of the parameters \mathbf{w} is given by Bayes' rule

$$\begin{aligned} p(\mathbf{w}|\mathbf{t}, X, \theta, \mathcal{H}_i) &= \frac{p(\mathbf{t}|X, \mathbf{w}, \theta, \mathcal{H}_i)p(\mathbf{w}|\theta, X, \mathcal{H}_i)}{p(\mathbf{t}|X, \theta, \mathcal{H}_i)} \\ &= \frac{p(\mathbf{t}|X, \mathbf{w}, \mathcal{H}_i)p(\mathbf{w}|\theta, \mathcal{H}_i)}{p(\mathbf{t}|X, \theta, \mathcal{H}_i)} \end{aligned}$$

- with

- $p(\mathbf{t}|X, \mathbf{w}, \mathcal{H}_i)$ likelihood and
- $p(\mathbf{w}|\theta, \mathcal{H}_i)$ prior parameters \mathbf{w} ,
- Denominator (normalizing constant) is independent of the parameters and is called **marginal likelihood**.

$$p(\mathbf{t}|X, \theta, \mathcal{H}_i) = \int p(\mathbf{t}|X, \mathbf{w}, \mathcal{H}_i)p(\mathbf{w}|\theta, \mathcal{H}_i)d\mathbf{w}$$

Recap: Model Selection at Mid Level

- Posterior of parameters θ is again given by Bayes' rule

$$\begin{aligned} p(\theta|\mathbf{t}, X, \mathcal{H}_i) &= \frac{p(\mathbf{t}|X, \theta, \mathcal{H}_i)p(\theta|X, \mathcal{H}_i)}{p(\mathbf{t}|X, \mathcal{H}_i)} \\ &= \frac{p(\mathbf{t}|X, \theta, \mathcal{H}_i)p(\theta|\mathcal{H}_i)}{p(\mathbf{t}|X, \mathcal{H}_i)} \end{aligned}$$

- where

- The marginal likelihood of the previous level $p(\mathbf{t}|X, \theta, \mathcal{H}_i)$ plays the role of the likelihood of this level.
- $p(\theta|\mathcal{H}_i)$ is the **hyperprior** (prior of the hyperparameters)
- Denominator (normalizing constant) is given by:

$$p(\mathbf{t}|X, \mathcal{H}_i) = \int p(\mathbf{t}|X, \theta, \mathcal{H}_i)p(\theta|\mathcal{H}_i)d\theta$$

Recap: Model Selection at Top Level

- At the top level, we calculate the posterior of the model

$$p(\mathcal{H}_i | \mathbf{t}, X) = \frac{p(\mathbf{t} | X, \mathcal{H}_i) p(\mathcal{H}_i)}{p(\mathbf{t} | X)}$$

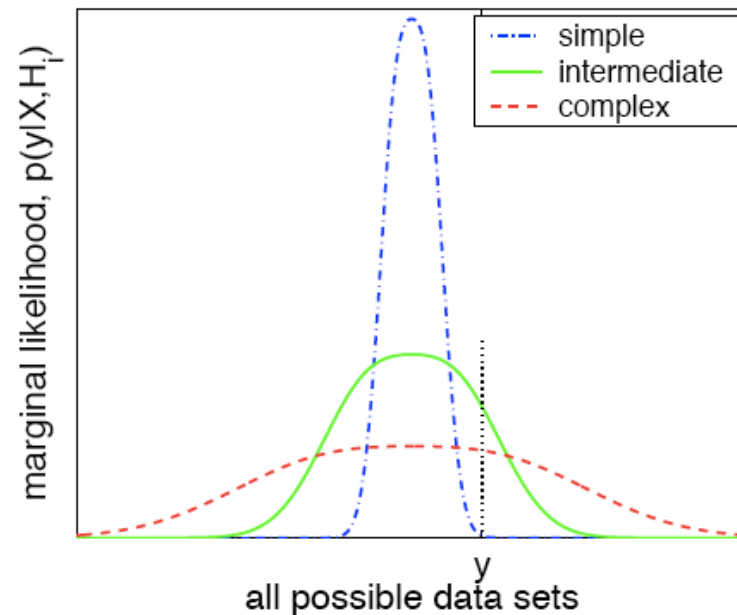
- where
 - Again, the denominator of the previous level $p(\mathbf{t} | X, \mathcal{H}_i)$ plays the role of the likelihood.
 - $p(\mathcal{H}_i)$ is the prior of the model structure.
 - Denominator (normalizing constant) is given by:

$$p(\mathbf{t} | X) = \sum_i p(\mathbf{t} | X, \mathcal{H}_i) p(\mathcal{H}_i)$$

Recap: Bayesian Model Selection

- Discussion

- Marginal likelihood is main difference to non-Bayesian methods
- It automatically incorporates a trade-off between the model fit and the model complexity:
 - A simple model can only account for a limited range of possible sets of target values - if a simple model fits well, it obtains a high posterior.
 - A complex model can account for a large range of possible sets of target values - therefore, it can never attain a very high posterior.



Topics of This Lecture

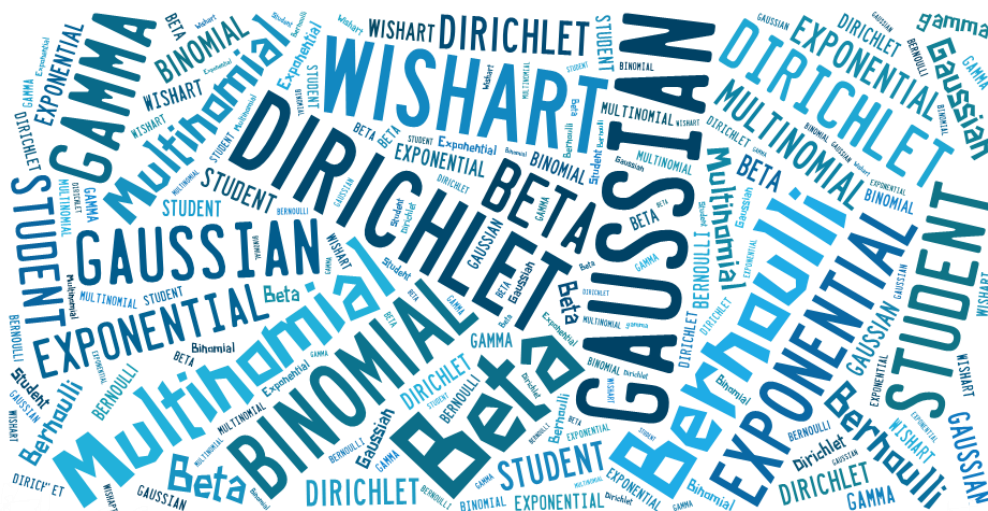
- **Probability Distributions**
 - Bayesian Estimation Reloaded
- **Binary Variables**
 - Bernoulli distribution
 - Binomial distribution
 - Beta distribution
- **Multinomial Variables**
 - Multinomial distribution
 - Dirichlet distribution
- **Continuous Variables**
 - Gaussian distribution
 - Gamma distribution
 - Student's t distribution
 - Exponential Family

Motivation

- Recall: Bayesian estimation

$$p(x|X) = \int p(x|\theta) \frac{p(X|\theta)p(\theta)}{\int p(X|\theta')p(\theta')d\theta'} d\theta$$

- So far, we have only done this for Gaussian distributions, where the integrals could be solved analytically.
- Now, let's also examine other distributions...



Conjugate Priors

- **Problem: How to evaluate the integrals?**
 - We will see that if likelihood and prior have the same functional form $c \cdot f(x)$, then the analysis will be greatly simplified and the integrals will be solvable in closed form.

$$\begin{aligned} p(X|\theta)p(\theta) &= \prod_{x_n} c_1 f(x_n, \theta) c_2 f(\theta, \alpha) \\ &= \prod_{x_n} c f(x_n, \theta, \alpha) \end{aligned}$$

- Such an algebraically convenient choice is called a **conjugate prior**. Whenever possible, we should use it.
- To do this, we need to know for each probability distribution what is its conjugate prior. \Rightarrow *Topic of this lecture.*
- **What to do when we cannot use the conjugate prior?**
 \Rightarrow *Use approximate inference methods. Next lecture...*

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Binary Variables

- **Example: Flipping a coin**

- Binary random variable $x \in \{0,1\}$
- Outcome heads: $x = 1$
- Outcome tails: $x = 0$
- Denote probability of landing heads by parameter μ

$$p(x = 1 | \mu) = \mu$$

- **Bernoulli distribution**

- Probability distribution over x :

$$\text{Bern}(x | \mu) = \mu^x (1 - \mu)^{1-x}$$

$$\mathbb{E}[x] = \mu$$

$$\text{var}[x] = \mu(1 - \mu)$$

The Binomial Distribution

- Now consider N coin flips
 - Probability of landing m heads: $p(m \text{ heads} | N, \mu)$

- **Binomial distribution**

$$\text{Bin}(m | N, \mu) = \binom{N}{m} \mu^m (1 - \mu)^{N-m}$$

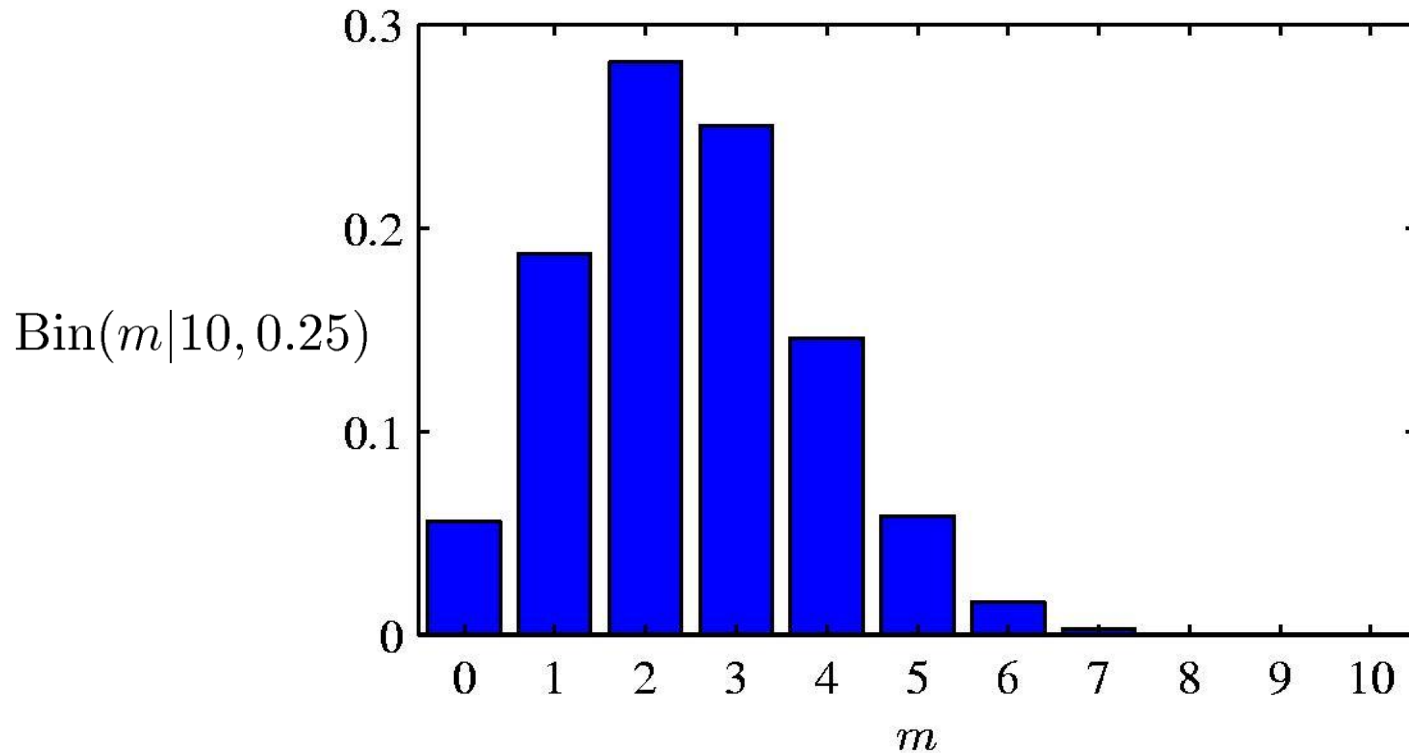
- **Properties**

$$\mathbb{E}[m] \equiv \sum_{m=0}^N m \text{Bin}(m | N, \mu) = N\mu$$

$$\text{var}[m] \equiv \sum_{m=0}^N (m - \mathbb{E}[m])^2 \text{Bin}(m | N, \mu) = N\mu(1 - \mu)$$

- **Note: Bernoulli is a special case of the Binomial for $n = 1$.**

Binomial Distribution: Visualization



Parameter Estimation: Maximum Likelihood

- **Maximum Likelihood for Bernoulli**

- Given a data set $\mathcal{D} = \{x_1, \dots, x_N\}$ of observed values for x .
- **Likelihood**

$$p(\mathcal{D}|\mu) = \prod_{n=1}^N p(x_n|\mu) = \prod_{n=1}^N \mu^{x_n} (1 - \mu)^{1-x_n}$$

$$\log p(\mathcal{D}|\mu) = \sum_{n=1}^N \log p(x_n|\mu) = \sum_{n=1}^N \{x_n \log \mu + (1 - x_n) \log(1 - \mu)\}$$

- **Observation**

- The log-likelihood depends on the observations x_n only through their sum.
- ⇒ $\sum_n x_n$ is a **sufficient statistic** for the Bernoulli distribution.

ML for Bernoulli Distribution

$$\log p(\mathcal{D}|\mu) = \sum_{n=1}^N \{x_n \log \mu + (1 - x_n) \log(1 - \mu)\}$$

$$\nabla_{\mu} \log p(\mathcal{D}|\mu) = \frac{1}{\mu} \sum_{n=1}^N x_n - \frac{1}{1 - \mu} \sum_{n=1}^N (1 - x_n) \stackrel{!}{=} 0$$

$$(1 - \mu) \sum_{n=1}^N x_n = \mu \sum_{n=1}^N (1 - x_n)$$

$$\sum_{n=1}^N x_n - \cancel{\mu \sum_{n=1}^N x_n} = N\mu - \cancel{\mu \sum_{n=1}^N x_n}$$

- **ML estimate:**

$$\mu_{\text{ML}} = \frac{1}{N} \sum_{n=1}^N x_n$$

ML for Bernoulli Distribution

- Maximum Likelihood estimate

$$\mu_{\text{ML}} = \frac{1}{N} \sum_{n=1}^N x_n = \frac{m}{N} \quad \text{for } m \text{ heads } (x_n = 1)$$

- Discussion

➤ Consider a data set $\mathcal{D} = \{1,1,1\}$. $\rightarrow \mu_{\text{ML}} = \frac{3}{3} = 1$

⇒ Prediction: *all* future tosses will land head up!

⇒ Overfitting to \mathcal{D} !

Bayesian Bernoulli: First Try

- Bayesian estimation

- We can improve the ML estimate by incorporating a prior for μ .
- How should such a prior look like?

- Consider the Bernoulli/Binomial form

$$p(\mathcal{D}|\mu) \propto \prod_{n=1}^N \mu^{x_n} (1 - \mu)^{1-x_n}$$

- If we choose a prior with the same functional form, then we will get a closed-form expression for the posterior; otherwise, a difficult numerical integration may be necessary.

- Most general form here:

$$p(\mu|a, b) \propto \mu^a (1 - \mu)^b$$

- This algebraically convenient choice is called a **conjugate prior**.

The Beta Distribution

- **Beta distribution**

- **Distribution over $\mu \in [0,1]$:**

$$\text{Beta}(\mu|a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \mu^{a-1} (1-\mu)^{b-1}$$

- **Where $\Gamma(x)$ is the gamma function**

$$\Gamma(x) \equiv \int_0^{\infty} u^{x-1} e^{-u} du$$

for which $\Gamma(x+1) = x!$ iff x is an integer.

$\Rightarrow \Gamma(x)$ is a continuous generalization of the factorial.

- **The Beta distribution generalizes the Binomial to arbitrary values of a and b , while keeping the same functional form.**
- **It is therefore a **conjugate prior** for the Bernoulli and Binomial.**

Beta Distribution

- Properties

- In general, the Beta distribution is a suitable model for the random behavior of percentages and proportions.

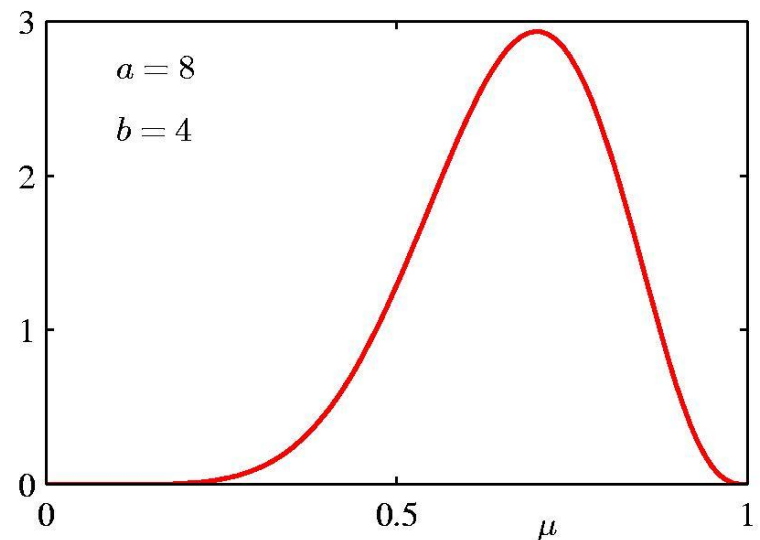
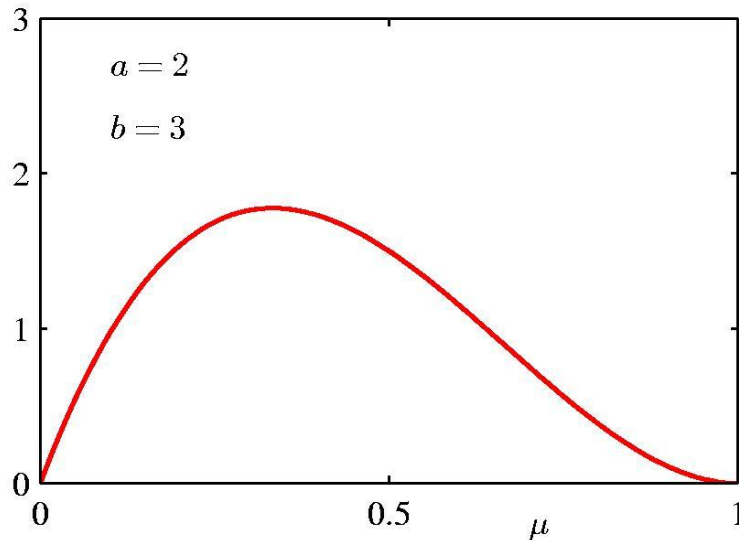
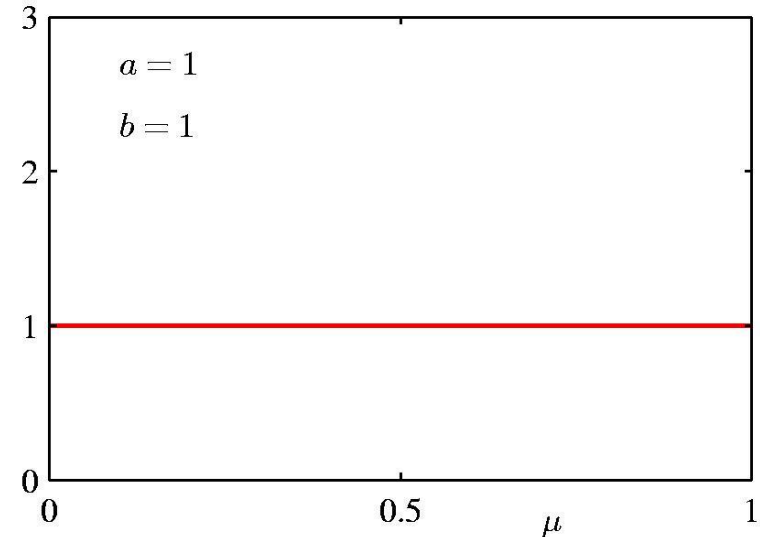
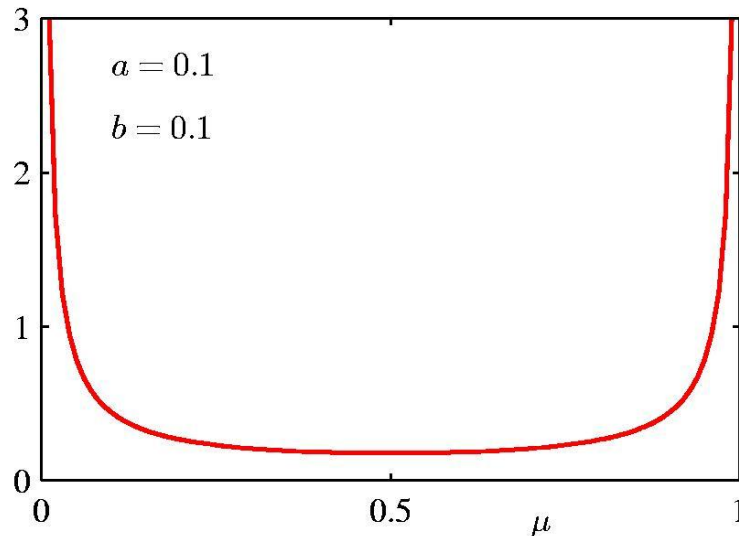
- Mean and variance

$$\mathbb{E}[\mu] = \frac{a}{a + b}$$

$$\text{var}[\mu] = \frac{ab}{(a + b)^2(a + b + 1)}$$

- The parameters a and b are often called **hyperparameters**, because they control the distribution of the parameter μ .
- General observation: if a distribution has K parameters, then the conjugate prior typically has $K+1$ hyperparameters.

Beta Distribution: Visualization



Bayesian Bernoulli

- Bayesian estimate

$$\begin{aligned} p(\mu|a_0, b_0, \mathcal{D}) &\propto p(\mathcal{D}|\mu)p(\mu|a_0, b_0) \\ &= \left(\prod_{n=1}^N \mu^{x_n} (1 - \mu)^{1-x_n} \right) \text{Beta}(\mu|a_0, b_0) \\ &\propto \mu^{m+a_0-1} (1 - \mu)^{(N-m)+b_0-1} \\ &\propto \text{Beta}(\mu|a_N, b_N) \end{aligned}$$

- This is again a Beta distribution with the parameters

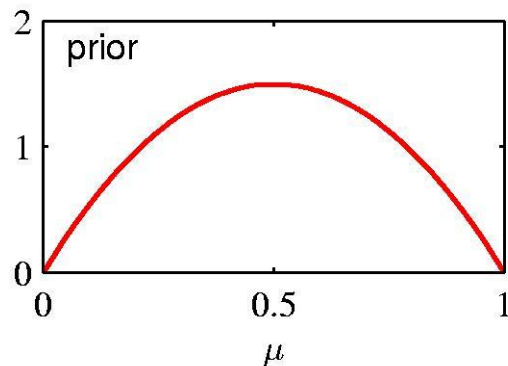
$$a_N = a_0 + m \quad b_N = b_0 + (N - m)$$

⇒ We can interpret the hyperparameters a and b as an **effective number of observations** for $x = 1$ and $x = 0$, respectively.

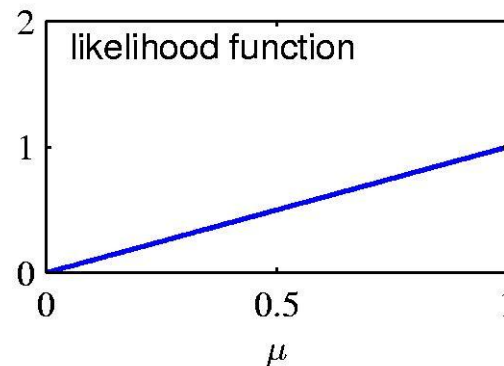
- Note: a and b need not be integers!

Sequential Estimation

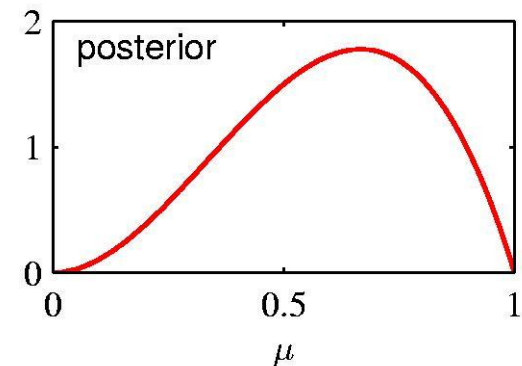
- **Prior · Likelihood = Posterior**
 - The posterior can act as a prior if we observe additional data.
 - The number of effective observations increases accordingly.
- **Example: Taking observations one at a time**



$$\text{Beta}(\mu | a = 2, b = 2)$$



$$\text{Bin}(m = 1 | N = 1, \mu)$$



$$\text{Beta}(\mu | a = 3, b = 2)$$

⇒ This sequential approach to learning naturally arises when we take a Bayesian viewpoint.

Properties of the Posterior

- Behavior in the limit of infinite data
 - As the size of the data set, N , increases

$$a_N = a_0 + m \rightarrow m$$

$$b_N = b_0 + N - m \rightarrow N - m$$

$$\mathbb{E}[\mu] = \frac{a_N}{a_N + b_N} \rightarrow \frac{m}{N} = \mu_{\text{ML}}$$

$$\text{var}[\mu] = \frac{a_N b_N}{(a_N + b_N)^2 (a_N + b_N + 1)} \rightarrow 0$$

⇒ As expected, the Bayesian result reduces to the ML result.

Prediction under the Posterior

- Predict the outcome of the next trial
 - “What is the probability that the next coin toss will land heads up?”
- ⇒ Evaluate the predictive distribution of x given the observed data set \mathcal{D} :

$$\begin{aligned} p(x = 1 | a_0, b_0, \mathcal{D}) &= \int_0^1 p(x = 1 | \mu) p(\mu | a_0, b_0, \mathcal{D}) \, d\mu \\ &= \int_0^1 \mu p(\mu | a_0, b_0, \mathcal{D}) \, d\mu \\ &= \mathbb{E}[\mu | a_0, b_0, \mathcal{D}] = \frac{a_N}{b_N} \end{aligned}$$

- Simple interpretation: total fraction of observations that correspond to $x = 1$.

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- **Multinomial Variables**
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Multinomial Variables

- **Multinomial variables**

- Variables that can take one of K possible distinct states
- Convenient: 1-of- K coding scheme: $\mathbf{x} = (0, 0, 1, 0, 0, 0)^T$

- **Generalization of the Bernoulli distribution**

- Distribution of \mathbf{x} with K outcomes

$$p(\mathbf{x}|\boldsymbol{\mu}) = \prod_{k=1}^K \mu_k^{x_k}$$

with the constraints

$$\forall k : \mu_k \geq 0 \quad \text{and} \quad \sum_{k=1}^K \mu_k = 1$$

Multinomial Variables

- **Properties**

- **Distribution is normalized**

$$\sum_{\mathbf{x}} p(\mathbf{x}|\boldsymbol{\mu}) = \sum_{k=1}^K \mu_k = 1$$

- **Expectation**

$$\mathbb{E}[\mathbf{x}|\boldsymbol{\mu}] = \sum_{\mathbf{x}} p(\mathbf{x}|\boldsymbol{\mu})\mathbf{x} = (\mu_1, \dots, \mu_K)^T = \boldsymbol{\mu}$$

- **Likelihood given a data set $\mathcal{D} = \{\mathbf{x}_1, \dots, \mathbf{x}_N\}$:**

$$p(\mathcal{D}|\boldsymbol{\mu}) = \prod_{n=1}^N \prod_{k=1}^K \mu_k^{x_{nk}} = \prod_{k=1}^K \mu_k^{(\sum_n x_{nk})} = \prod_{k=1}^K \mu_k^{m_k}$$

where m_k is the number of cases for which \mathbf{x}_n has output k .

ML Parameter Estimation

- Maximum Likelihood solution for μ

- Need to maximize

$$\log p(\mathcal{D}|\mu) = \log \prod_{k=1}^K \mu_k^{m_k} = \sum_{k=1}^K m_k \log \mu_k$$

Under the constraint $\sum_k \mu_k = 1$

- Solution with Lagrange multiplier

$$\arg \max_{\mu} \sum_{k=1}^K m_k \log \mu_k + \lambda \left(\sum_{k=1}^K \mu_k - 1 \right)$$

- Setting the derivative to zero yields

$$\mu_k = -m_k / \lambda \quad \mu_k^{\text{ML}} = \frac{m_k}{N}$$

The Multinomial Distribution

- **Multinomial Distribution**

- **Joint distribution over m_1, \dots, m_K conditioned on μ and N**

$$\text{Mult}(m_1, m_2, \dots, m_K | \mu, N) = \binom{N}{m_1 m_2 \dots m_K} \prod_{k=1}^K \mu_k^{m_k}$$

with the normalization coefficient

$$\binom{N}{m_1 m_2 \dots m_K} = \frac{N!}{m_1! m_2! \dots m_K!}$$

- **Properties**

$$\begin{aligned}\mathbb{E}[m_k] &= N \mu_k \\ \text{var}[m_k] &= N \mu_k (1 - \mu_k) \\ \text{cov}[m_j, m_k] &= -N \mu_j \mu_k\end{aligned}$$

Bayesian Multinomial

- Conjugate prior for the Multinomial

- Introduce a family of prior distributions for the parameters $\{\mu_k\}$ of the Multinomial.
- The conjugate prior is given by

$$p(\mu|\alpha) \propto \prod_{k=1}^K \mu_k^{\alpha_k - 1}$$

with the constraints

$$\forall k : 0 \leq \mu_k \leq 1 \quad \text{and} \quad \sum_{k=1}^K \mu_k = 1$$

The Dirichlet Distribution

- Dirichlet Distribution

- Multivariate generalization of the Beta distribution

$$\text{Dir}(\boldsymbol{\mu}|\boldsymbol{\alpha}) = \frac{\Gamma(\alpha_0)}{\Gamma(\alpha_1)\cdots\Gamma(\alpha_K)} \prod_{k=1}^K \mu_k^{\alpha_k-1} \quad \text{with} \quad \alpha_0 = \sum_{k=1}^K \alpha_k$$

- Properties

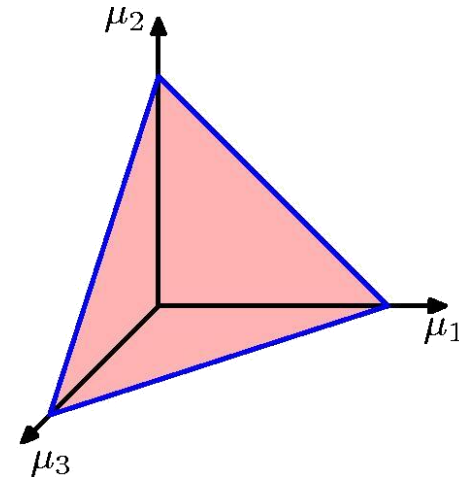
- The Dirichlet distribution over K variables is confined to a $K-1$ dimensional simplex.

- Expectations:

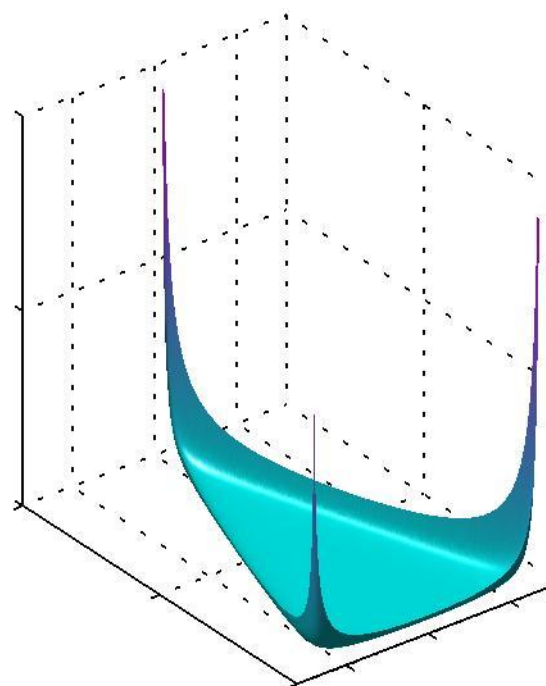
$$\mathbb{E}[\mu_k] = \frac{\alpha_k}{\alpha_0}$$

$$\text{var}[\mu_k] = \frac{\alpha_k(\alpha_0 - \alpha_k)}{\alpha_0^2(\alpha_0 + 1)}$$

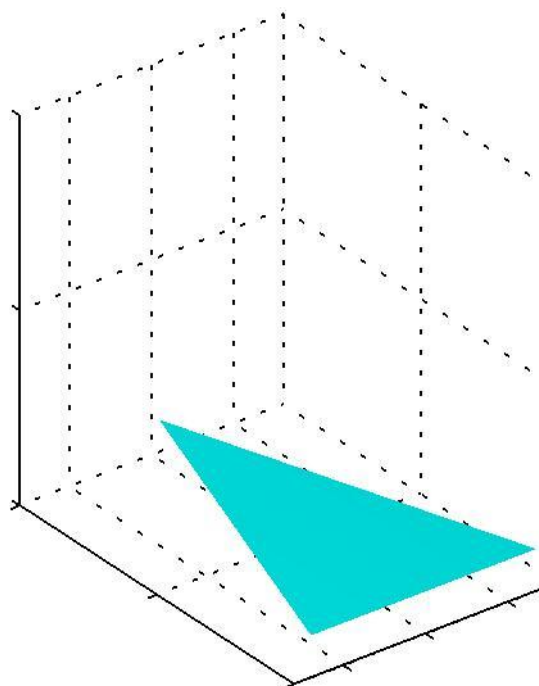
$$\text{COV}[\mu_j, \mu_k] = -\frac{\alpha_j \alpha_k}{\alpha_0^2(\alpha_0 + 1)}$$



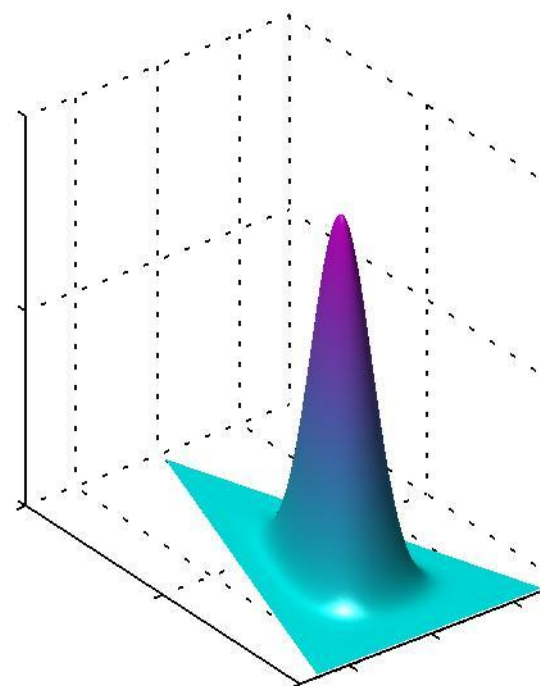
Dirichlet Distribution: Visualization



$$\alpha_k = 10^{-1}$$



$$\alpha_k = 10^0$$



$$\alpha_k = 10^1$$

Bayesian Multinomial

- Posterior distribution over the parameters $\{\mu_k\}$

$$p(\boldsymbol{\mu}|\mathcal{D}, \boldsymbol{\alpha}) \propto p(\mathcal{D}|\boldsymbol{\mu})p(\boldsymbol{\mu}|\boldsymbol{\alpha}) \propto \prod_{k=1}^K \mu_k^{\alpha_k + m_k - 1}$$

- Comparison with the definition gives us the normalization factor

$$\begin{aligned} p(\boldsymbol{\mu}|\mathcal{D}, \boldsymbol{\alpha}) &= \text{Dir}(\boldsymbol{\mu}|\boldsymbol{\alpha} + \mathbf{m}) \\ &= \frac{\Gamma(\alpha_0 + N)}{\Gamma(\alpha_1 + m_1) \cdots \Gamma(\alpha_K + m_K)} \prod_{k=1}^K \mu_k^{\alpha_k + m_k - 1} \end{aligned}$$

⇒ We can interpret the parameters α_k of the Dirichlet prior as an **effective number of observations** of $x_k = 1$.

Topics of This Lecture

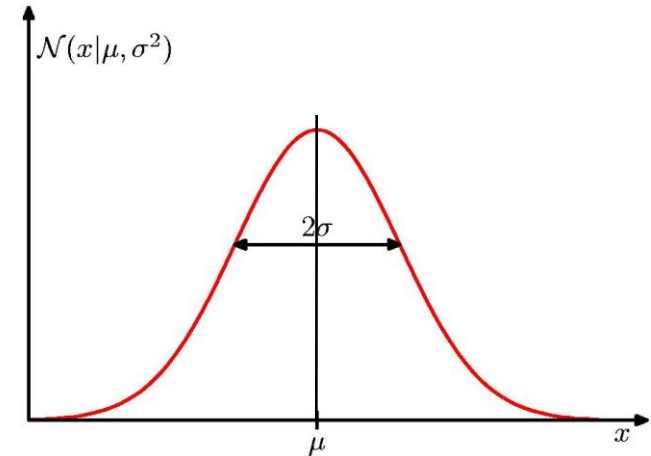
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The Gaussian Distribution

- One-dimensional case

- Mean μ
- Variance σ^2

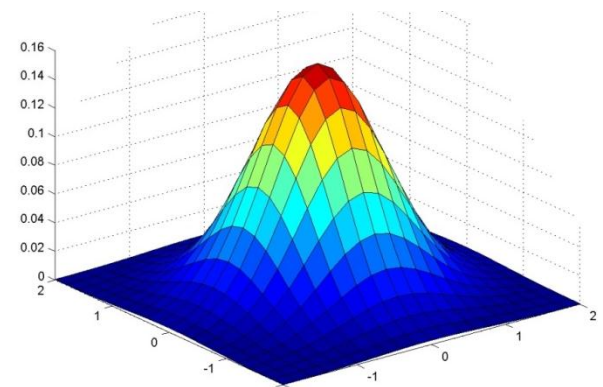
$$\mathcal{N}(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left\{ -\frac{(x - \mu)^2}{2\sigma^2} \right\}$$



- Multi-dimensional case

- Mean μ
- Covariance Σ

$$\mathcal{N}(\mathbf{x}|\mu, \Sigma) = \frac{1}{(2\pi)^{D/2} |\Sigma|^{1/2}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \mu)^T \Sigma^{-1} (\mathbf{x} - \mu) \right\}$$

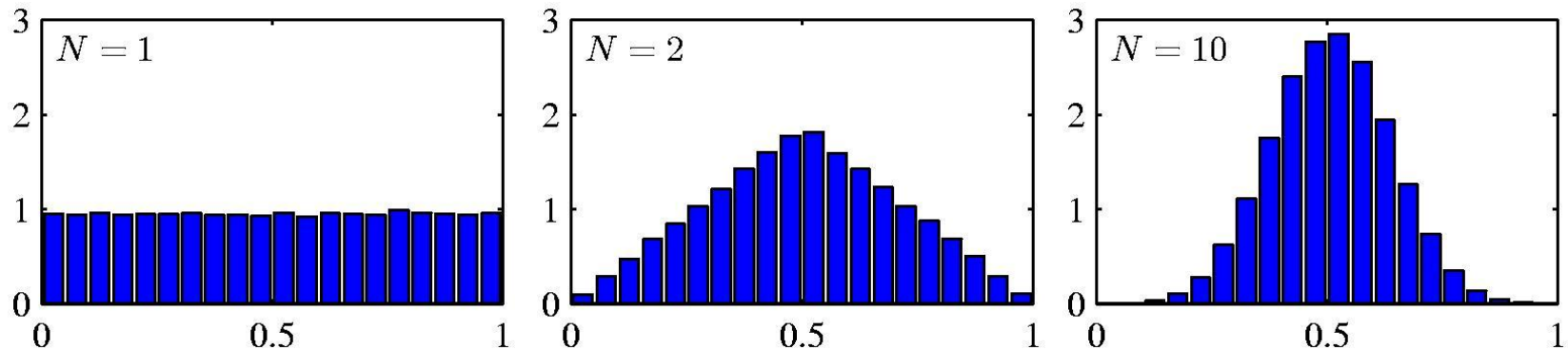


Gaussian Distribution - Properties

- **Central Limit Theorem**

- “The distribution of the sum of N i.i.d. random variables becomes increasingly Gaussian as N grows.”
- In practice, the convergence to a Gaussian can be very rapid.
- This makes the Gaussian interesting for many applications.

- **Example: N uniform $[0,1]$ random variables.**



Gaussian Distribution - Properties

- Properties

$$\mathbb{E}[\mathbf{x}] = \boldsymbol{\mu}$$

$$\mathbb{E}[\mathbf{x}\mathbf{x}^T] = \boldsymbol{\mu}\boldsymbol{\mu}^T + \boldsymbol{\Sigma}$$

$$\text{cov}[\mathbf{x}] = \mathbb{E} [(\mathbf{x} - \mathbb{E}[\mathbf{x}])(\mathbf{x} - \mathbb{E}[\mathbf{x}])^T] = \boldsymbol{\Sigma}$$

- Limitations

- Distribution is intrinsically unimodal, i.e. it is unable to provide a good approximation to multimodal distributions.

⇒ We will see how to fix that with mixture distributions later...

Bayes' Theorem for Gaussian Variables

- **Marginal and Conditional Gaussians**

- Suppose we are given a Gaussian prior $p(\mathbf{x})$ and a Gaussian conditional distribution $p(\mathbf{y}|\mathbf{x})$ (a **linear Gaussian model**)

$$p(\mathbf{x}) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Lambda}^{-1})$$

$$p(\mathbf{y}|\mathbf{x}) = \mathcal{N}(\mathbf{y}|\mathbf{A}\mathbf{x} + \mathbf{b}, \mathbf{L}^{-1})$$

- From this, we can compute

$$p(\mathbf{y}) = \mathcal{N}(\mathbf{y}|\mathbf{A}\boldsymbol{\mu} + \mathbf{b}, \mathbf{L}^{-1} + \mathbf{A}\boldsymbol{\Lambda}^{-1}\mathbf{A}^T)$$

$$p(\mathbf{x}|\mathbf{y}) = \mathcal{N}(\mathbf{x}|\boldsymbol{\Sigma}\{\mathbf{A}^T\mathbf{L}(\mathbf{y} - \mathbf{b}) + \boldsymbol{\Lambda}\boldsymbol{\mu}\}, \boldsymbol{\Sigma})$$

where

$$\boldsymbol{\Sigma} = (\boldsymbol{\Lambda} + \mathbf{A}^T\mathbf{L}\mathbf{A})^{-1}$$

⇒ Closed-form solution for (Gaussian) marginal and posterior.

Maximum Likelihood for the Gaussian

- **Maximum Likelihood**

- Given i.i.d. data $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_N)^T$, the log likelihood function is given by

$$\begin{aligned} \log p(\mathbf{X}|\mu, \Sigma) &= -\frac{ND}{2} \log(2\pi) - \frac{N}{2} \log |\Sigma| \\ &\quad - \frac{1}{2} \sum_{n=1}^N (\mathbf{x}_n - \mu)^T \Sigma^{-1} (\mathbf{x}_n - \mu) \end{aligned}$$

- **Sufficient statistics**

- The likelihood depends on the data set only through

$$\sum_{n=1}^N \mathbf{x}_n \qquad \sum_{n=1}^N \mathbf{x}_n \mathbf{x}_n^T$$

- Those are the **sufficient statistics** for the Gaussian distribution.

ML for the Gaussian

- **Setting the derivative to zero**

$$\frac{\partial}{\partial \boldsymbol{\mu}} \ln p(\mathbf{X} | \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \sum_{n=1}^N \boldsymbol{\Sigma}^{-1} (\mathbf{x}_n - \boldsymbol{\mu}) = 0$$

- **Solve to obtain**

$$\boldsymbol{\mu}_{\text{ML}} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}_n.$$

- **And similarly, but a bit more involved**

$$\boldsymbol{\Sigma}_{\text{ML}} = \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n - \boldsymbol{\mu}_{\text{ML}})(\mathbf{x}_n - \boldsymbol{\mu}_{\text{ML}})^{\text{T}}.$$

ML for the Gaussian

- Comparison with true results
 - Under the true distribution, we obtain

$$\begin{aligned}\mathbb{E}[\boldsymbol{\mu}_{\text{ML}}] &= \boldsymbol{\mu} \\ \mathbb{E}[\boldsymbol{\Sigma}_{\text{ML}}] &= \frac{N-1}{N} \boldsymbol{\Sigma}.\end{aligned}$$

⇒ The ML estimate for the covariance is biased and underestimates the true covariance!

- Therefore define the following unbiased estimator

$$\tilde{\boldsymbol{\Sigma}} = \frac{1}{N-1} \sum_{n=1}^N (\mathbf{x}_n - \boldsymbol{\mu}_{\text{ML}})(\mathbf{x}_n - \boldsymbol{\mu}_{\text{ML}})^{\text{T}}.$$

Bayesian Inference for the Gaussian

- Let's begin with a simple example

- Consider a single Gaussian random variable x .
- Assume σ^2 is known and the task is to infer the mean μ .
- Given i.i.d. data $\mathbf{X} = (x_1, \dots, x_N)^T$, the likelihood function for μ is given by

$$p(\mathbf{X}|\mu) = \prod_{n=1}^N p(x_n|\mu) = \frac{1}{(2\pi\sigma^2)^{N/2}} \exp \left\{ -\frac{1}{2\sigma^2} \sum_{n=1}^N (x_n - \mu)^2 \right\}.$$

- The likelihood function has a Gaussian shape as a function of μ .
- ⇒ The **conjugate prior** for this case is again a Gaussian.

$$p(\mu) = \mathcal{N}(\mu|\mu_0, \sigma_0^2).$$

Bayesian Inference for the Gaussian

- Combined with a Gaussian prior over μ

$$p(\mu) = \mathcal{N}(\mu | \mu_0, \sigma_0^2).$$

- This results in the posterior

$$p(\mu | \mathbf{x}) \propto p(\mathbf{x} | \mu) p(\mu).$$

- Completing the square over μ , we can derive that

$$p(\mu | \mathbf{x}) = \mathcal{N}(\mu | \mu_N, \sigma_N^2)$$

where

$$\mu_N = \frac{\sigma^2}{N\sigma_0^2 + \sigma^2} \mu_0 + \frac{N\sigma_0^2}{N\sigma_0^2 + \sigma^2} \mu_{\text{ML}},$$

$$\mu_{\text{ML}} = \frac{1}{N} \sum_{n=1}^N x_n$$

$$\frac{1}{\sigma_N^2} = \frac{1}{\sigma_0^2} + \frac{N}{\sigma^2}.$$

Visualization of the Results

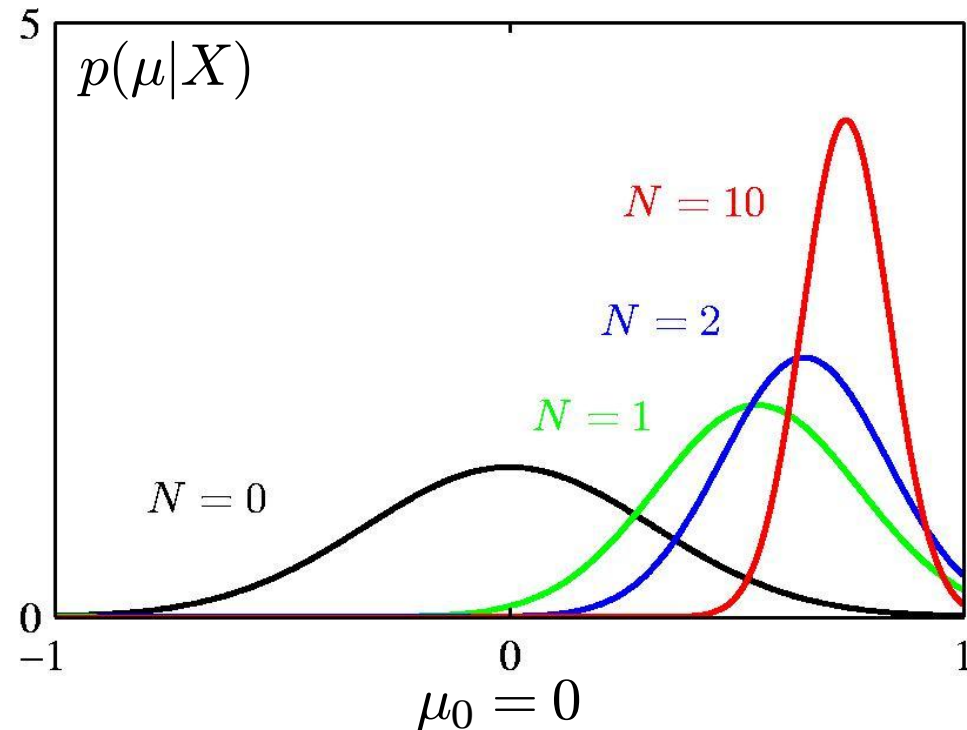
- Bayes estimate:

$$\mu_N = \frac{\sigma^2 \mu_0 + N \sigma_0^2 \mu_{\text{ML}}}{\sigma^2 + N \sigma_0^2}$$

$$\frac{1}{\sigma_N^2} = \frac{1}{\sigma_0^2} + \frac{N}{\sigma^2}$$

- Behavior for large N

	$N = 0$	$N \rightarrow \infty$
μ_N	μ_0	μ_{ML}
σ_N^2	σ_0^2	0



Bayesian Inference for the Gaussian

- **More complex case**

- Now assume μ is known and the precision λ shall be inferred.
- The likelihood function for $\lambda = 1/\sigma^2$ is given by

$$p(\mathbf{X}|\lambda) = \prod_{n=1}^N \mathcal{N}(x_n|\mu, \lambda^{-1}) \propto \lambda^{N/2} \exp \left\{ -\frac{\lambda}{2} \sum_{n=1}^N (x_n - \mu)^2 \right\}.$$

- This has the shape of a **Gamma function** of λ .

The Gamma Distribution

- **Gamma distribution**

- Product of a power of λ and the exponential of a linear function of λ .

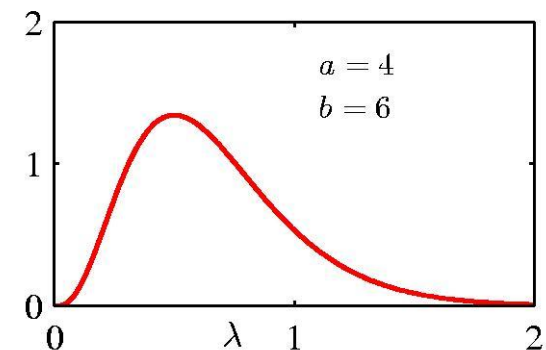
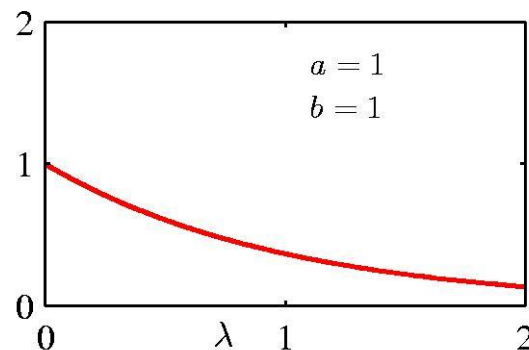
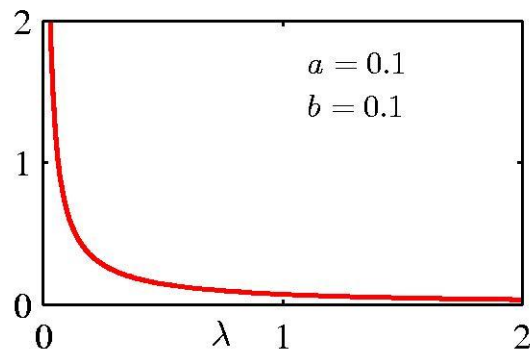
$$\text{Gam}(\lambda|a, b) = \frac{1}{\Gamma(a)} b^a \lambda^{a-1} \exp(-b\lambda)$$

- **Properties**

- Finite integral if $a > 0$ and the distribution itself is finite if $a \geq 1$.

- **Moments** $\mathbb{E}[\lambda] = \frac{a}{b}$ $\text{var}[\lambda] = \frac{a}{b^2}$

- **Visualization**



Bayesian Inference for the Gaussian

- **Bayesian estimation**

- **Combine a Gamma prior $\text{Gam}(\lambda|a_0, b_0)$ with the likelihood function to obtain**

$$p(\lambda|\mathbf{X}) \propto \lambda^{a_0-1} \lambda^{N/2} \exp \left\{ -b_0 \lambda - \frac{\lambda}{2} \sum_{n=1}^N (x_n - \mu)^2 \right\}$$

- **We recognize this again as a Gamma function $\text{Gam}(\lambda|a_N, b_N)$ with**

$$a_N = a_0 + \frac{N}{2}$$

$$b_N = b_0 + \frac{1}{2} \sum_{n=1}^N (x_n - \mu)^2 = b_0 + \frac{N}{2} \sigma_{\text{ML}}^2.$$

Bayesian Inference for the Gaussian

- Even more complex case
 - Assume that both μ and λ are unknown
 - The joint likelihood function is given by

$$p(\mathbf{X}|\mu, \lambda) = \prod_{n=1}^N \left(\frac{\lambda}{2\pi} \right)^{1/2} \exp \left\{ -\frac{\lambda}{2} (x_n - \mu)^2 \right\}$$
$$\propto \left[\lambda^{1/2} \exp \left(-\frac{\lambda \mu^2}{2} \right) \right]^N \exp \left\{ \lambda \mu \sum_{n=1}^N x_n - \frac{\lambda}{2} \sum_{n=1}^N x_n^2 \right\}.$$

⇒ Need a prior with the same functional dependence on μ and λ .

The Gaussian-Gamma Distribution

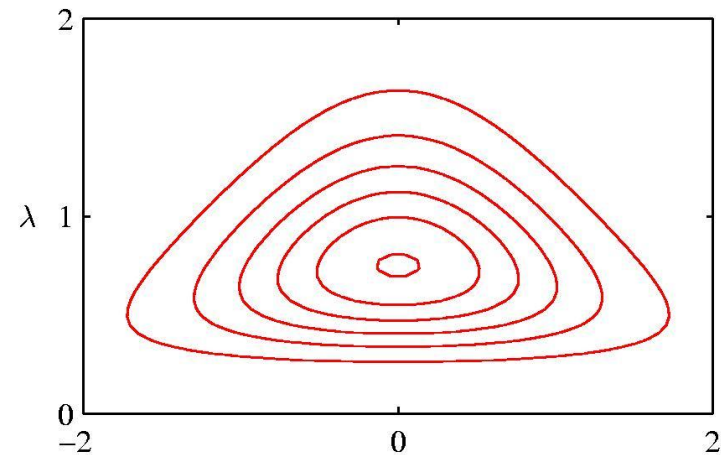
- **Gaussian-Gamma distribution**

$$p(\mu, \lambda) = \mathcal{N}(\mu | \mu_0, (\beta\lambda)^{-1}) \text{Gam}(\lambda | a, b)$$

$$\propto \underbrace{\exp\left\{-\frac{\beta\lambda}{2}(\mu - \mu_0)^2\right\}}_{\text{Quadratic in } \mu} \underbrace{\lambda^{a-1} \exp\{-b\lambda\}}_{\text{Gamma distribution over } \lambda}$$

- Quadratic in μ .
- Linear in λ .
- Gamma distribution over λ .
- Independent of μ .

- **Visualization**



Bayesian Inference for the Gaussian

- **Multivariate conjugate priors**

- μ unknown, Λ known: $p(\mu)$ **Gaussian**.

- Λ unknown, μ known: $p(\Lambda)$ **Wishart**,

$$\mathcal{W}(\Lambda | \mathbf{W}, \nu) = B |\Lambda|^{(\nu - D - 1)/2} \exp\left(-\frac{1}{2} \text{Tr}(\mathbf{W}^{-1} \Lambda)\right).$$

- Λ and μ unknown: $p(\mu, \Lambda)$ **Gaussian-Wishart**,

$$p(\mu, \Lambda | \mu_0, \beta, \mathbf{W}, \nu) = \mathcal{N}(\mu | \mu_0, (\beta \Lambda)^{-1}) \mathcal{W}(\Lambda | \mathbf{W}, \nu)$$

Student's t-Distribution

- Gaussian estimation

- The conjugate prior for the precision of a Gaussian is a Gamma distribution.
- Suppose we have a univariate Gaussian $\mathcal{N}(x | \mu, \tau^{-1})$ together with a Gamma prior $\text{Gam}(\tau | a, b)$.
- By integrating out the precision, obtain the **marginal distribution**

$$\begin{aligned} p(x | \mu, a, b) &= \int_0^{\infty} \mathcal{N}(x | \mu, \tau^{-1}) \text{Gam}(\tau | a, b) d\tau \\ &= \int_0^{\infty} \mathcal{N}(x | \mu, (\eta\lambda)^{-1}) \text{Gam}(\eta | \nu/2, \nu/2) d\eta \end{aligned}$$

- This corresponds to an **infinite mixture of Gaussians** having the same mean, but different precision.

Student's t-Distribution

- Student's t-Distribution

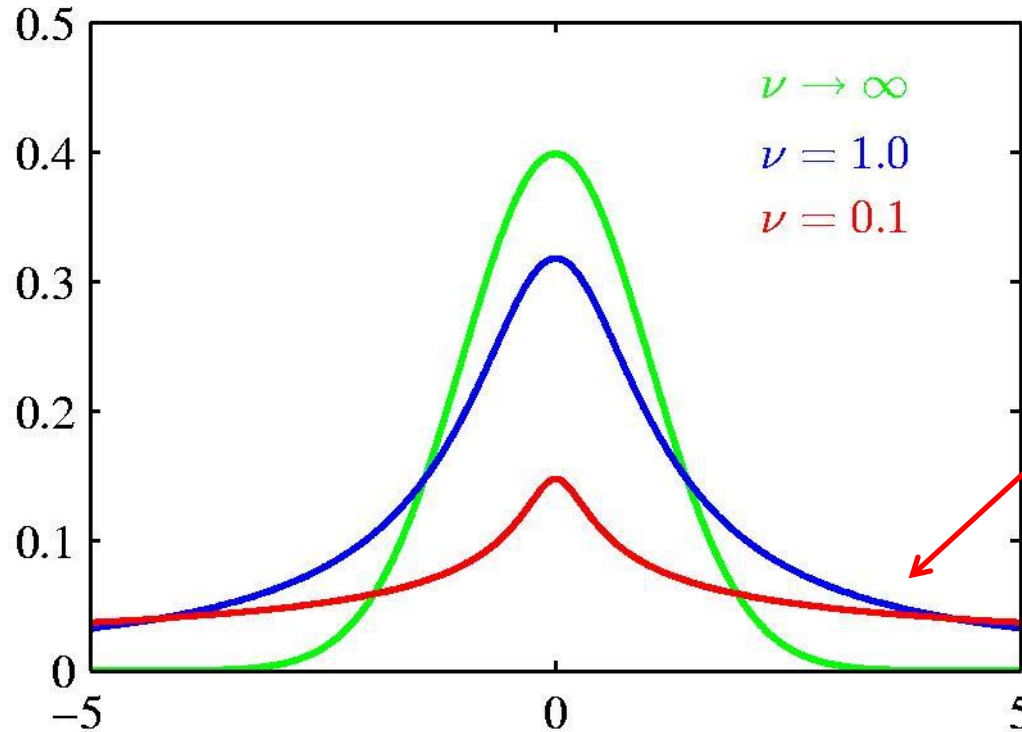
- We reparametrize the infinite mixture of Gaussians to get

$$\text{St}(x|\mu, \lambda, \nu) = \frac{\Gamma(\nu/2 + 1/2)}{\Gamma(\nu/2)} \left(\frac{\lambda}{\pi\nu}\right)^{1/2} \left[1 + \frac{\lambda(x - \mu)^2}{\nu}\right]^{-\nu/2 - 1/2}$$

- Parameters

- “Precision” $\lambda = a/b$
- “Degrees of freedom” $\nu = 2a$.

Student's t-Distribution: Visualization



**Longer-tailed
distribution!**

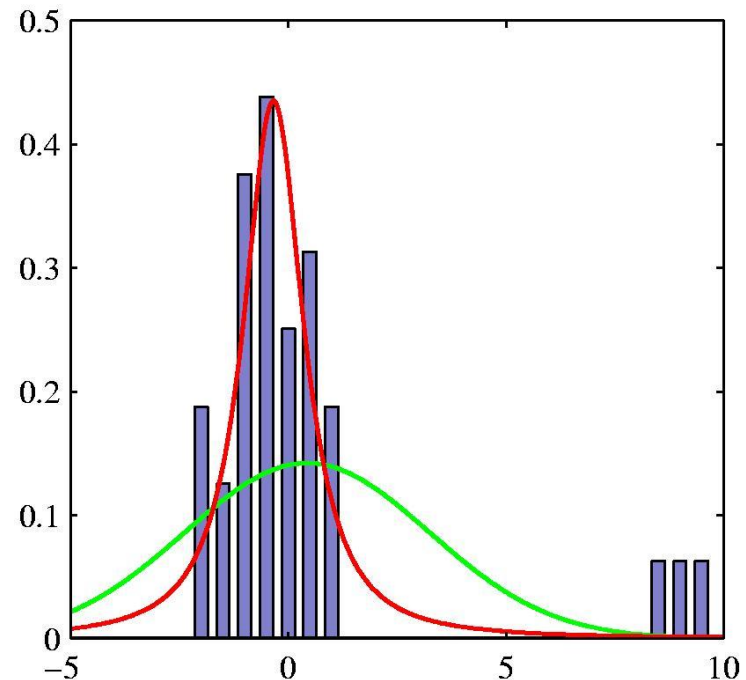
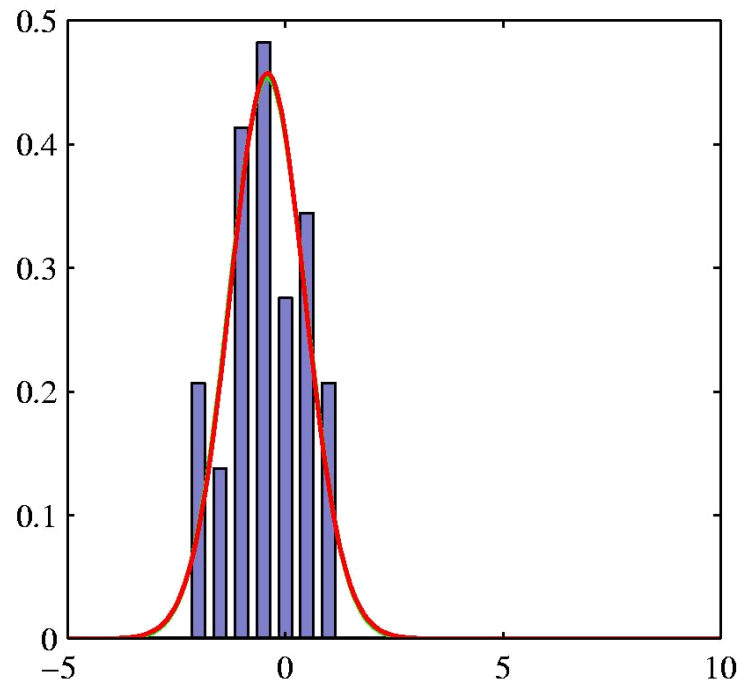
**⇒ More robust
to outliers...**

- Behavior**

	$\nu = 1$	$\nu \rightarrow \infty$
$\text{St}(x \mu, \lambda, \nu)$	Cauchy	$\mathcal{N}(x \mu, \lambda^{-1})$

Student's t-Distribution

- Robustness to outliers: **Gaussian** vs **t-distribution**.



⇒ The t-distribution is much less sensitive to outliers, can be used for robust regression.

⇒ Downside: ML solution for t-distribution requires EM algorithm.

Student's t-Distribution: Multivariate Case

- Multivariate case in D dimensions

$$\begin{aligned} \text{St}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Lambda}, \nu) &= \int_0^\infty \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, (\eta\boldsymbol{\Lambda})^{-1}) \text{Gam}(\eta|\nu/2, \nu/2) d\eta \\ &= \frac{\Gamma(D/2 + \nu/2)}{\Gamma(\nu/2)} \frac{|\boldsymbol{\Lambda}|^{1/2}}{(\pi\nu)^{D/2}} \left[1 + \frac{\Delta^2}{\nu} \right]^{-D/2 - \nu/2} \end{aligned}$$

where $\Delta^2 = (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Lambda} (\mathbf{x} - \boldsymbol{\mu})$ is the Mahalanobis distance.

- Properties

$$\mathbb{E}[\mathbf{x}] = \boldsymbol{\mu}, \quad \text{if } \nu > 1$$

$$\text{cov}[\mathbf{x}] = \frac{\nu}{(\nu - 2)} \boldsymbol{\Lambda}^{-1}, \quad \text{if } \nu > 2$$

$$\text{mode}[\mathbf{x}] = \boldsymbol{\mu}$$

References and Further Reading

- Probability distributions and their properties are described in Chapter 2 of Bishop's book.

Christopher M. Bishop
Pattern Recognition and Machine Learning
Springer, 2006

